

# 32K x 8 AutoStore™ nvSRAM with Real Time Clock

## Features

- nvSRAM Combined With Integrated Real-Time Clock Functions (RTC, Watchdog Timer, Clock Alarm, Power Monitor)
- Capacitor or Battery Backup for RTC
- 25, 45 ns Read Access and R/W Cycle Time
- Unlimited Read/Write Endurance
- Automatic Nonvolatile STORE on Power Loss
- Nonvolatile STORE Under Hardware or Software Control
- Automatic RECALL to SRAM on Power Up
- Unlimited RECALL Cycles
- 200K STORE Cycles
- 20-Year Nonvolatile Data Retention
- Single 3V +20%, -10% Power Supply
- Commercial and Industrial Temperatures
- 48-pin 300-mil SSOP Package (RoHS-Compliant)

## Description

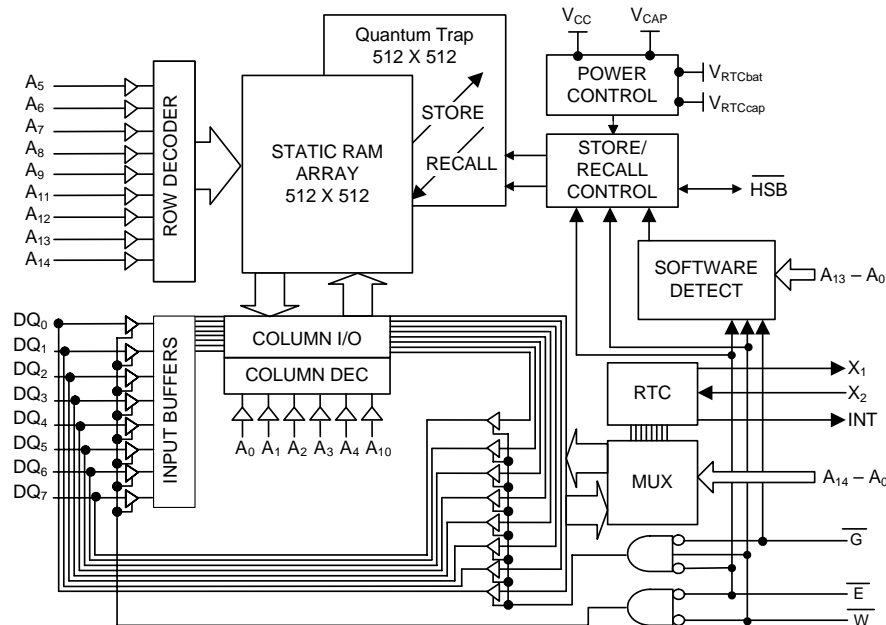
The Cypress STK17T88 combines a 256 Kb nonvolatile static RAM (nvSRAM) with a full-featured real-time clock in a reliable, monolithic integrated circuit.

The 256 Kb nvSRAM is a fast static RAM with a nonvolatile Quantum Trap storage element included with each memory cell.

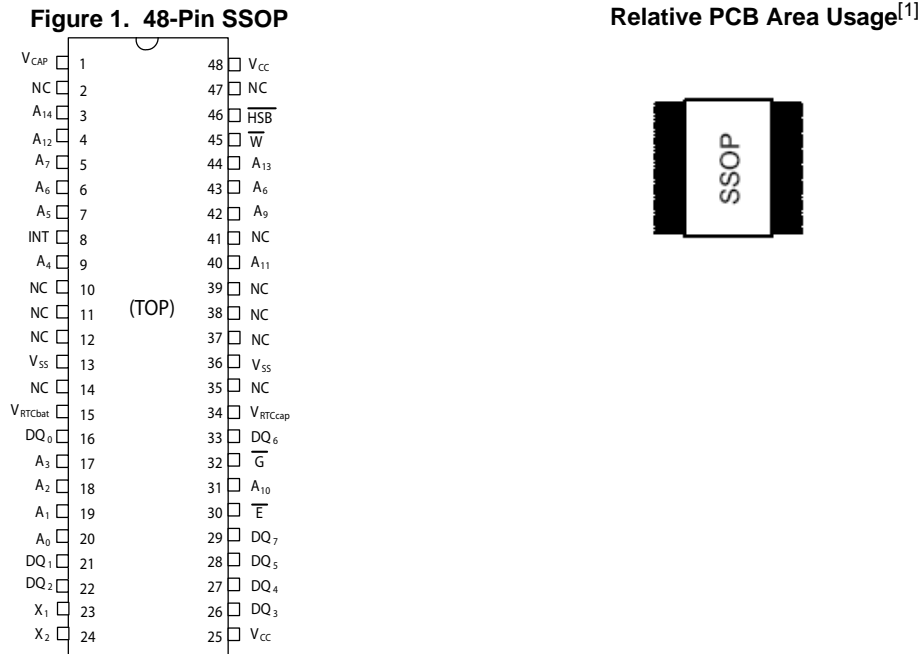
The SRAM provides the fast access and cycle times, ease of use and unlimited read and write endurance of a normal SRAM. Data transfers automatically to the nonvolatile storage cells when power loss is detected (the *STORE* operation). On power up, data is automatically restored to the SRAM (the *RECALL* operation). Both *STORE* and *RECALL* operations are also available under software control.

The real time clock function provides an accurate clock with leap year tracking and a programmable, high accuracy oscillator. The Alarm function is programmable for one-time alarms or periodic minutes, hours, or days alarms. There is also a programmable watchdog timer for processor control.

## Logic Block Diagram



## Pin Configurations



## Pin Descriptions

Pin Name	IO Type	Description
A <sub>14</sub> -A <sub>0</sub>	Input	<b>Address:</b> The 15 address inputs select one of 32,768 bytes in the nvSRAM array or one of 16 bytes in the clock register map.
DQ <sub>7</sub> -DQ <sub>0</sub>	I/O	<b>Data:</b> Bi-directional 8-bit data bus for accessing the nvSRAM and RTC.
E	Input	<b>Chip Enable:</b> The active low E input selects the device.
W	Input	<b>Write Enable:</b> The active low W enables data on the DQ pins to be written to the address location selected on the falling edge of E.
G	Input	<b>Output Enable:</b> The active low G input enables the data output buffers during read cycles. De-asserting G high caused the DQ pins to tri-state.
X <sub>1</sub>	Output	<b>Crystal Connection, drives crystal on startup.</b>
X <sub>2</sub>	Input	<b>Crystal Connection for 32.768 kHz crystal.</b>
V <sub>RTCcap</sub>	Power Supply	<b>Capacitor supplied backup RTC supply voltage (Left unconnected if V<sub>RTCbat</sub> is used).</b>
V <sub>RTCbat</sub>	Power Supply	<b>Battery supplied backup RTC supply voltage (Left unconnected if V<sub>RTCcap</sub> is used).</b>
V <sub>CC</sub>	Power Supply	<b>Power:</b> 3.0V, +20%, -10%
HSB	I/O	<b>Hardware Store Busy:</b> When low this output indicates a Store is in progress. When pulled low external to the chip, it initiates a nonvolatile STORE operation. A weak pull up resistor keeps this pin high if not connected. (Connection Optional).
INT	Output	<b>Interrupt Control:</b> Can be programmed to respond to the clock alarm, the watchdog timer and the power monitor. Programmable to either active high (push/pull) or active low (open-drain)
V <sub>CAP</sub>	Power Supply	<b>Autostore™ Capacitor:</b> Supplies power to nvSRAM during power loss to store data from SRAM to nonvolatile storage elements.
V <sub>SS</sub>	Power Supply	<b>Ground</b>
NC	No Connect	<b>Unlabeled pins have no internal connections.</b>

**Note**

1. For detailed package size specifications, see [Package Diagram](#) on page 21.

## Absolute Maximum Ratings

Voltage on Input Relative to Ground.....	-0.5V to 4.1V
Voltage on Input Relative to $V_{SS}$ .....	-0.5V to ( $V_{CC} + 0.5V$ )
Voltage on $DQ_{0-7}$ or $\overline{HSB}$ .....	-0.5V to ( $V_{CC} + 0.5V$ )
Temperature under Bias .....	-55°C to 125°C
Junction Temperature .....	-55°C to 140°C
Storage Temperature .....	-65°C to 150°C
Power Dissipation.....	1W
DC Output Current (1 output at a time, 1s duration)....	15 mA

**Note:** Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

## RF (SSOP-48) Package Thermal Characteristics

$\theta_{jc}$  6.2 C/W;  $\theta_{ja}$  51.1 [0fpm], 44.7 [200fpm], 41.8 C/W [500fpm]

## DC Characteristics

( $V_{CC} = 2.7V-3.6V$ )

Symbol	Parameter	Commercial		Industrial		Units	Notes
		Min	Max	Min	Max		
$I_{CC1}$	Average $V_{CC}$ Current		65 50		70 55	mA mA	$t_{AVAV} = 25$ ns $t_{AVAV} = 45$ ns Dependent on output loading and cycle rate. Values obtained without output loads.
$I_{CC2}$	Average $V_{CC}$ Current during STORE		3		3	mA	All Inputs Don't Care, $V_{CC} = \max$ Average current for duration of STORE cycle ( $t_{STORE}$ )
$I_{CC3}$	Average $V_{CC}$ Current at $t_{AVAV} = 200$ ns 3V, 25°C, Typical		10		10	mA	$\overline{W} \geq (V_{CC} - 0.2V)$ All Other Inputs Cycling at CMOS Levels Dependent on output loading and cycle rate. Values obtained without output loads.
$I_{CC4}$	Average $V_{CAP}$ Current during AutoStore™ Cycle		3		3	mA	All Inputs Don't Care Average current for duration of STORE cycle ( $t_{STORE}$ )
$I_{SB}$	$V_{CC}$ Standby Current (Standby, Stable CMOS Levels)		3		3	mA	$\overline{E} \geq (V_{CC} - 0.2V)$ All Others $V_{IN} \leq 0.2V$ or $\geq (V_{CC} - 0.2V)$ Standby current level after nonvolatile cycle complete
$I_{ILK}$	Input Leakage Current		$\pm 1$		$\pm 1$	$\mu A$	$V_{CC} = \max$ $V_{IN} = V_{SS}$ to $V_{CC}$
$I_{OLK}$	Off-State Output Leakage Current		$\pm 1$		$\pm 1$	$\mu A$	$V_{CC} = \max$ $V_{IN} = V_{SS}$ to $V_{CC}$ , $\overline{E}$ or $\overline{G} \geq V_{IH}$
$V_{IH}$	Input Logic “1” Voltage	2.0	$V_{CC} + 0.5$	2.0	$V_{CC} + 0.5$	V	All Inputs
$V_{IL}$	Input Logic “0” Voltage	$V_{SS} - 0.5$	0.8	$V_{SS} - 0.5$	0.8	V	All Inputs

Note: The  $\overline{HSB}$  pin has  $I_{OUT} = -10\mu A$  for  $V_{OH}$  of 2.4V, this parameter is characterized but not tested.

Note: The INT is open-drain and does not source or sink high current when interrupt Register bit D3 is below.

**DC Characteristics** (continued)

( $V_{CC} = 2.7V-3.6V$ )

Symbol	Parameter	Commercial		Industrial		Units	Notes
		Min	Max	Min	Max		
$V_{OH}$	Output Logic "1" Voltage	2.4		2.4		V	$I_{OUT} = -2\text{ mA}$
$V_{OL}$	Output Logic "0" Voltage		0.4		0.4	V	$I_{OUT} = 4\text{ mA}$
$T_A$	Operating Temperature	0	70	-40	85	°C	
$V_{CC}$	Operating Voltage	2.7	3.6	2.7	3.6	V	3.0V +20%, -10%
$V_{CAP}$	Storage Capacitance	17	57	17	57	μF	Between $V_{CAP}$ pin and $V_{SS}$ , 5V rated.
$NV_C$	Nonvolatile STORE operations	200		200		K	
$DATA_R$	Data Retention	20		20		Years	At 55°C

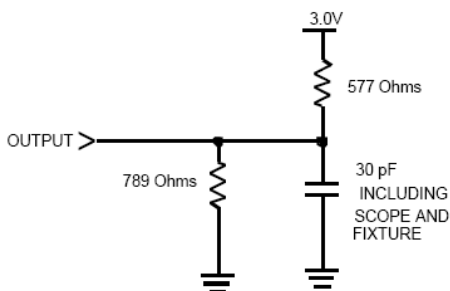
**AC Test Conditions**

Input Pulse Levels .....0V to 3V  
 Input Rise and Fall Times ..... $\leq 5\text{ns}$   
 Input and Output Timing Reference Levels ..... 1.5V  
 Output Load.....See [Figure 2](#) and [Figure 3](#)

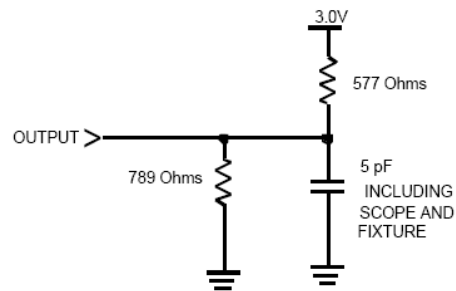
**Capacitance**

Symbol	Parameter <sup>[2]</sup>	Max	Units	Conditions
$C_{IN}$	Input Capacitance	7	pF	$\Delta V = 0\text{ to }3V$
$C_{OUT}$	Output Capacitance	7	pF	$\Delta V = 0\text{ to }3V$

**Figure 2. AC Output Loading**



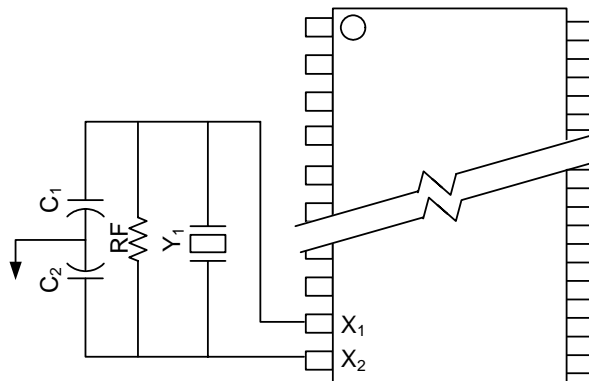
**Figure 3. AC Output Loading for Tristate Specs ( $T_{HZ}$ ,  $t_{LZ}$ ,  $t_{WLQZ}$ ,  $t_{WHQZ}$ ,  $t_{GLQX}$ ,  $t_{GHQZ}$ )**



**Note**  
 2. These parameters are guaranteed but not tested.

**RTC DC Characteristics**

Symbol	Parameter	Commercial		Industrial		Units	Notes
		Min	Max	Min	Max		
IBAK	RTC Backup Current	—	300	—	350	nA	From either VRTCcap or VRTCbat
VRTCbat	RTC Battery Pin Voltage	1.8	3.3	1.8	3.3	V	Typical = 3.0 Volts during normal operation
VRTCcap	RTC Capacitor Pin Voltage	1.2	2.7	1.2	2.7	V	Typical = 2.4 Volts during normal operation
tOSCS	RTC Oscillator time to start	—	10	—	10	sec	At Minimum Temperature from Power up or Enable
		—	5	—	5	sec	At 25°C from Power up or Enable

**Figure 4. RTC Component Configuration**

**Recommended Values**
 $Y_1 = 32.768 \text{ KHz}$ 
 $RF = 10M \text{ Ohm}$ 
 $C_1 = 0$  (install cap footprint, but leave unloaded)

 $C_2 = 56 \text{ pF} \pm 10\%$  (do not vary from this value)

SRAM READ Cycles #1 and #2

NO.	Symbols			Parameter	STK17T88-25		STK17T88-45		Units
	#1	#2	Alt.		Min	Max	Min	Max	
1		$t_{ELQV}$	$t_{ACS}$	Chip Enable Access Time		25		45	ns
2	$t_{AVAV}^{[3]}$	$t_{ELEH}^{[5]}$	$t_{RC}$	Read Cycle Time	25		45		ns
3	$t_{AVQV}^{[4]}$	$t_{AVQV}^{[6]}$	$t_{AA}$	Address Access Time		25		45	ns
4		$t_{GLQV}$	$t_{OE}$	Output Enable to Data Valid		12		20	ns
5	$t_{AXQX}^{[4]}$	$t_{AXQX}$	$t_{OH}$	Output Hold after Address Change	3		3		ns
6		$t_{ELQX}$	$t_{LZ}$	Address Change or Chip Enable to Output Active	3		3		ns
7		$t_{EHQZ}$	$t_{HZ}$	Address Change or Chip Disable to Output Inactive		10		15	ns
8		$t_{GLQX}$	$t_{OLZ}$	Output Enable to Output Active	0		0		ns
9		$t_{GHQZ}^{[5]}$	$t_{OHZ}$	Output Disable to Output Inactive		10		15	ns
10		$t_{ELICCL}^{[3]}$	$t_{PA}$	Chip Enable to Power Active	0		0		ns
11		$t_{EHICCH}^{[3]}$	$t_{PS}$	Chip Disable to Power Standby		25		45	ns

Figure 5. SRAM READ Cycle #1: Address Controlled<sup>[3,4,6]</sup>

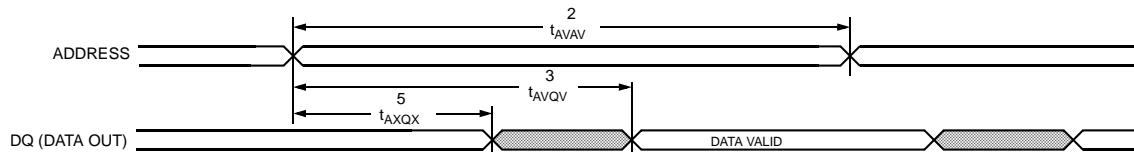
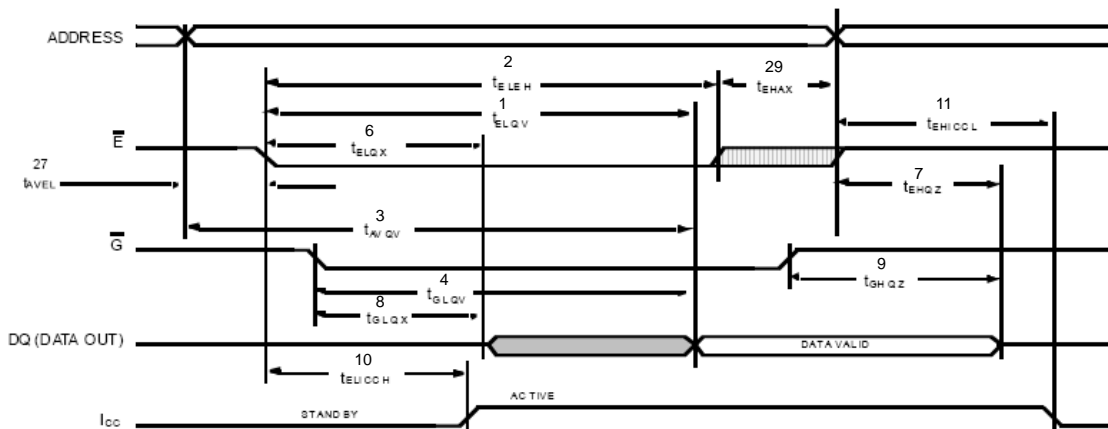


Figure 6. SRAM READ Cycle #2:  $\bar{E}$  and  $\bar{G}$  Controlled<sup>[6]</sup>



Notes

- 3.  $\bar{W}$  must be high during SRAM READ cycles.
- 4. Device is continuously selected with  $\bar{E}$  and  $\bar{G}$  both low
- 5. Measured  $\pm 200\text{mV}$  from steady state output voltage.
- 6. HSB must remain high during READ and WRITE cycles.

SRAM WRITE Cycles #1 and #2

NO.	Symbols			Parameter	STK17T88-25		STK17T88-45		Units
	#1	#2	Alt.		Min	Max	Min	Max	
12	$t_{AVAV}$	$t_{AVAV}$	$t_{WC}$	Write Cycle Time	25		45		ns
13	$t_{WLWH}$	$t_{WLEH}$	$t_{WP}$	Write Pulse Width	20		30		ns
14	$t_{ELWH}$	$t_{ELEH}$	$t_{CW}$	Chip Enable to End of Write	20		30		ns
15	$t_{DVWH}$	$t_{DVEH}$	$t_{DW}$	Data Set-up to End of Write	10		15		ns
16	$t_{WHDX}$	$t_{EHDX}$	$t_{DH}$	Data Hold after End of Write	0		0		ns
17	$t_{AVWH}$	$t_{AVEH}$	$t_{AW}$	Address Set-up to End of Write	20		30		ns
18	$t_{AVWL}$	$t_{AVEL}$	$t_{AS}$	Address Set-up to Start of Write	0		0		ns
19	$t_{WHAX}$	$t_{EHAX}$	$t_{WR}$	Address Hold after End of Write	0		0		ns
20	$t_{WLQZ}$		$t_{WZ}$	Write Enable to Output Disable		10		15	ns
21	$t_{WHQX}$		$t_{OW}$	Output Active after End of Write	3		3		ns

Figure 7. SRAM WRITE Cycle #1:  $\bar{W}$  Controlled<sup>[7, 8]</sup>

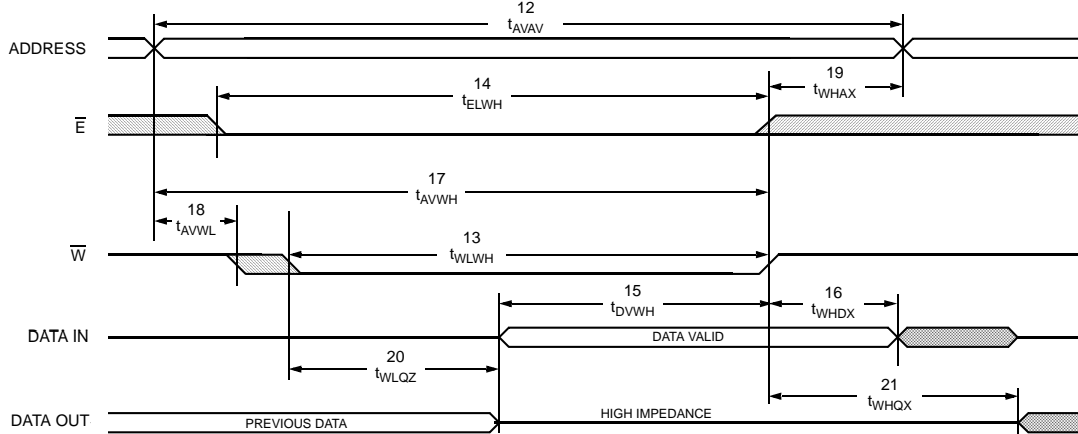
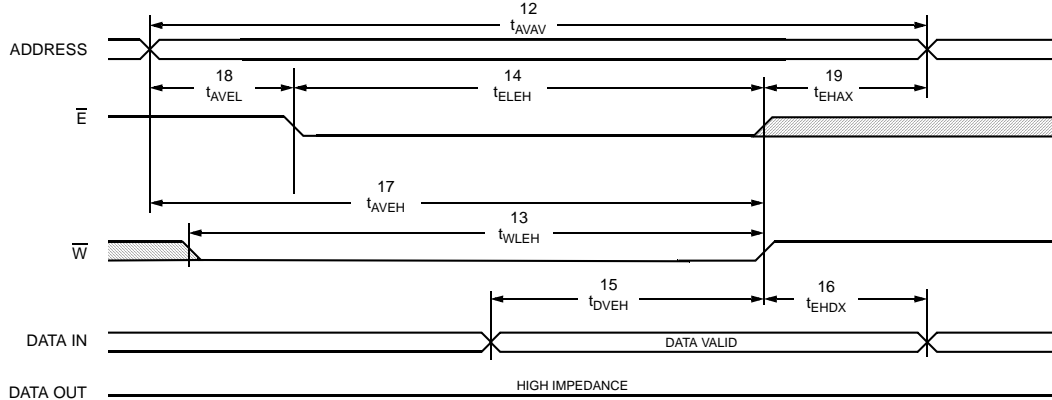


Figure 8. SRAM WRITE Cycle #2:  $\bar{E}$  Controlled<sup>[7, 8]</sup>



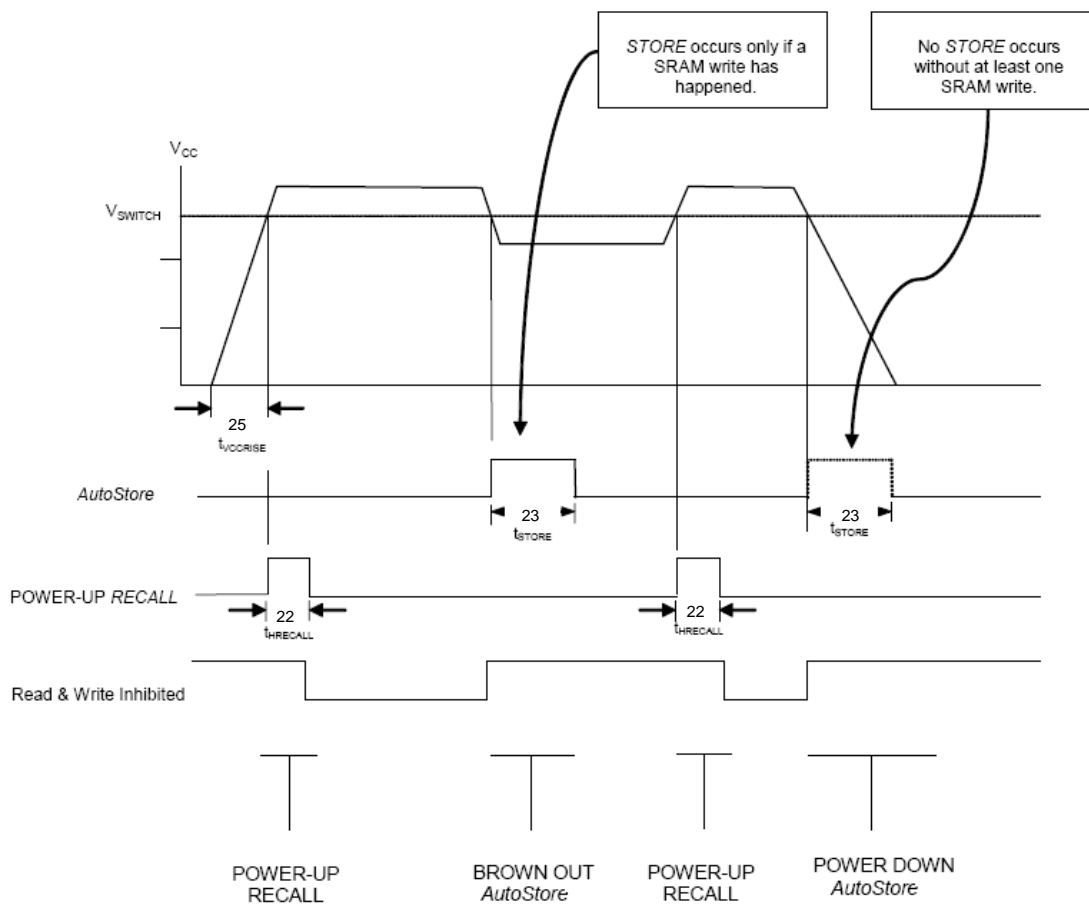
Notes

- 7. If  $\bar{W}$  is low when  $\bar{E}$  goes low, the outputs remain in the high-impedance state.
- 8.  $\bar{E}$  or  $\bar{W}$  must be  $\geq V_{IH}$  during address transitions.

### AutoStore/Power Up RECALL

NO.	Symbols		Parameter	STK17T88		Units	Notes
	Standard	Alternate		Min	Max		
22	$t_{HRECALL}$		Power up <i>RECALL</i> Duration		40	ms	9
23	$t_{STORE}$	$t_{HLHZ}$	<i>STORE</i> Cycle Duration		12.5	ms	10, 11
24	$V_{SWITCH}$		Low Voltage Trigger Level		2.65	V	
25	$V_{CCRISE}$		$V_{CC}$ Rise Time	150		$\mu$ S	

Figure 9. AutoStore Power Up RECALL



NOTE: Read and Write cycles will be ignored during STORE, RECALL and while  $V_{CC}$  is below  $V_{SWITCH}$

**Notes**

- 9.  $t_{HRECALL}$  starts from the time  $V_{CC}$  rises above  $V_{SWITCH}$
- 10. If an SRAM WRITE has not taken place since the last nonvolatile cycle, no STORE will take place
- 11. Industrial Grade Devices require 15 ms Max.

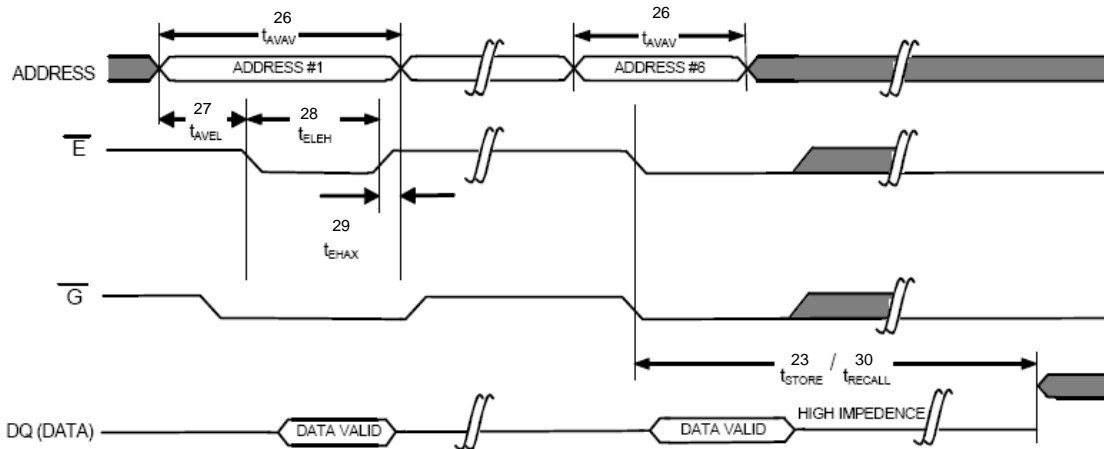


### Software-Controlled STORE/RECALL Cycle

In the following table, the software controlled STORE and RECALL cycle parameters are listed. [12, 13]

NO.	Symbols		Parameter	STK17T88-35		STK17T88-45		Units	Notes
	$\bar{E}$ Cont	Alternate		Min	Max	Min	Max		
26	$t_{AVAV}$	$t_{RC}$	STORE / RECALL Initiation Cycle Time	25		45		ns	13
27	$t_{AVEL}$	$t_{AS}$	Address Set-up Time	0		0		ns	
28	$t_{ELEH}$	$t_{CW}$	Clock Pulse Width	20		30		ns	
29	$t_{EHAX}$		Address Hold Time	1		1		ns	
30	$t_{RECALL}$		RECALL Duration		100		100	ms	

Figure 10. Software Store/Recall Cycle:  $\bar{E}$  CONTROLLED<sup>[13]</sup>



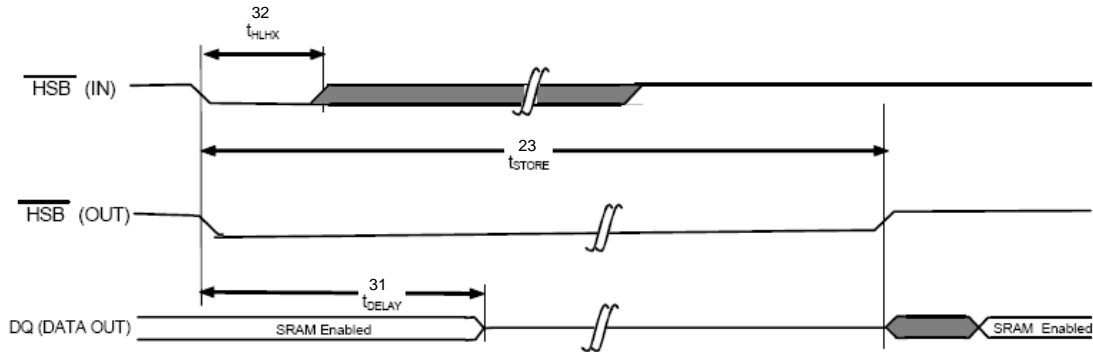
**Notes**

- 12. The software sequence is clocked on the falling edge of  $\bar{E}$  controlled READs
- 13. The six consecutive addresses must be read in the order listed in the Software STORE/RECALL Mode Selection Table. W must be high during all six consecutive cycles.

### Hardware STORE Cycle

NO.	Symbols		Parameter	STK17T88		Units	Notes
	Standard	Alternate		Min	Max		
31	t <sub>DELAY</sub>	t <sub>HLQZ</sub>	Hardware STORE to SRAM Disabled	1	70	μs	14
32	t <sub>HLHX</sub>		Hardware STORE Pulse Width	15		ns	

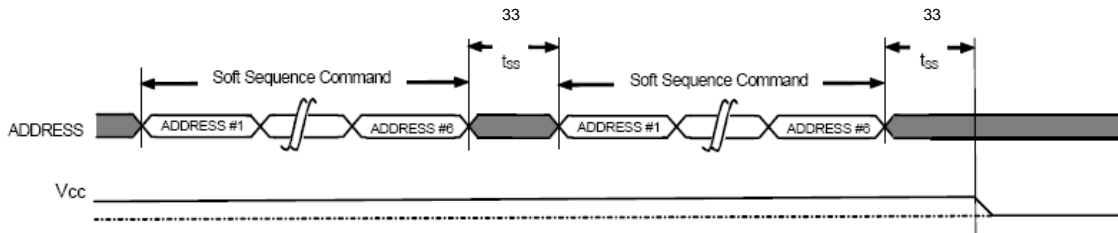
Figure 11. Hardware STORE Cycle



### Soft Sequence Commands

NO.	Symbols	Parameter	STK17T88		Units	Notes
	Standard		Min	Max		
33	t <sub>SS</sub>	Soft Sequence Processing Time		70	μs	15, 16

Figure 12. Soft Sequence Command



**Notes**

- 14. On a hardware STORE initiation, SRAM operation continues to be enabled for time t<sub>DELAY</sub> to allow read/write cycles to complete
- 15. This is the amount of time that it takes to take action on a soft sequence command. V<sub>cc</sub> power must remain high to effectively register command.
- 16. Commands like Store and Recall lock out I/O until operation is complete which further increases this time. See specific command

**MODE Selection**

$\bar{E}$	$\bar{W}$	$\bar{G}$	A <sub>14</sub> -A <sub>0</sub>	Mode	I/O	Power	Notes
H	X	X	X	Not Selected	Output High Z	Standby	
L	H	L	X	Read SRAM	Output Data	Active	
L	L	X	X	Write SRAM	Input Data	Active	
L	H	L	0x0E38 0x31C7 0x03E0 0x3C1F 0x303F 0x0FC0	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM Nonvolatile Store	Output Data Output Data Output Data Output Data Output Data Output High Z	Active	17,18, 19
						I <sub>CC2</sub>	
L	H	L	0x0E38 0x31C7 0x03E0 0x3C1F 0x303F 0x0C63	Read SRAM Read SRAM Read SRAM Read SRAM Read SRAM Nonvolatile Recall	Output Data Output Data Output Data Output Data Output Data Output High Z	Active	17,18, 19

**Notes**

17. The six consecutive addresses must be in the order listed.  $\bar{W}$  must be high during all six consecutive cycles to enable a nonvolatile cycle.  
 18. While there are 15 addresses on the STK17T88, only the lower 13 are used to control software modes.  
 19. I/O state depends on the state of  $\bar{G}$ . The I/O table shown assumes  $\bar{G}$  low.

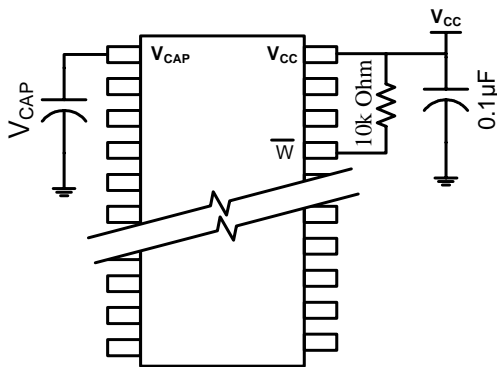
## nvSRAM Operation

The STK17T88 nvSRAM is made up of two functional components paired in the same physical cell. These are the SRAM memory cell and a nonvolatile QuantumTrap™ cell. The SRAM memory cell operates like a standard fast static RAM. Data in the SRAM can be transferred to the nonvolatile cell (the STORE operation), or from the nonvolatile cell to SRAM (the RECALL operation). This unique architecture allows all cells to be stored and recalled in parallel. During the STORE and RECALL operations SRAM READ and WRITE operations are inhibited. The STK17T88 supports unlimited read and writes like a typical SRAM. In addition, it provides unlimited RECALL operations from the nonvolatile cells and up to 200K STORE operations.

### SRAM READ

The STK17T88 performs a READ cycle whenever  $\bar{E}$  and  $\bar{G}$  are low while  $\bar{W}$  and  $\overline{HSB}$  are high. The address specified on pins  $A_{0-14}$  determine which of the 32,768 data bytes are accessed. When the READ is initiated by an address transition, the outputs are valid after a delay of  $t_{AVQV}$  (READ cycle #1). If the READ is initiated by  $\bar{E}$  and  $\bar{G}$ , the outputs are valid at  $t_{ELQV}$  or at  $t_{GLQV}$ , whichever is later (READ cycle #2). The data outputs repeatedly respond to address changes within the  $t_{AVQV}$  access time without the need for transitions on any control input pins, and remain valid until another address change or until  $\bar{E}$  or  $\bar{G}$  is brought high, or  $\bar{W}$  and  $\overline{HSB}$  is brought low.

Figure 13. AutoStore Mode



### SRAM WRITE

A WRITE cycle is performed whenever  $\bar{E}$  and  $\bar{W}$  are low and  $\overline{HSB}$  is high. The address inputs must be stable prior to entering the WRITE cycle and must remain stable until either  $\bar{E}$  or  $\bar{W}$  goes high at the end of the cycle. The data on the common I/O pins  $DQ_{0-7}$  are written into memory if it is valid  $t_{DVVH}$  before the end of a  $\bar{W}$  controlled WRITE or  $t_{DVEH}$  before the end of an  $\bar{E}$  controlled WRITE.

It is recommended that  $\bar{G}$  be kept high during the entire WRITE cycle to avoid data bus contention on common I/O lines. If  $\bar{G}$  is left low, internal circuitry turns off the output buffers  $t_{WLQZ}$  after  $\bar{W}$  goes low.

### AutoStore Operation

The STK17T88 stores data to nvSRAM using one of three storage operations. These three operations are Hardware Store

(activated by  $\overline{HSB}$ ), Software Store (activated by an address sequence), and AutoStore (on power down).

AutoStore operation, a unique feature of Cypress QuantumTrap technology that is a standard feature on the STK17T88.

During normal operation, the device draws current from  $V_{CC}$  to charge a capacitor connected to the  $V_{CAP}$  pin. This stored charge is used by the chip to perform a single STORE operation. If the voltage on the  $V_{CC}$  pin drops below  $V_{SWITCH}$ , the part automatically disconnects the  $V_{CAP}$  pin from  $V_{CC}$ . A STORE operation is initiated with power provided by the  $V_{CAP}$  capacitor.

Figure 5 shows the proper connection of the storage capacitor ( $V_{CAP}$ ) for automatic store operation. Refer to the DC Characteristics table for the size of the capacitor. The voltage on the  $V_{CAP}$  pin is driven to 5V by a charge pump internal to the chip. A pull up should be placed on  $\bar{W}$  to hold it inactive during power up.

To reduce unneeded nonvolatile stores, AutoStore and Hardware Store operations are ignored unless at least one WRITE operation has taken place since the most recent STORE or RECALL cycle. Software initiated STORE cycles are performed regardless of whether a WRITE operation has taken place. The  $\overline{HSB}$  signal can be monitored by the system to detect an AutoStore cycle is in progress.

### Hardware STORE ( $\overline{HSB}$ ) Operation

The STK17T88 provides the  $\overline{HSB}$  pin for controlling and acknowledging the STORE operations. The  $\overline{HSB}$  pin can be used to request a hardware STORE cycle. When the  $\overline{HSB}$  pin is driven low, the STK17T88 conditionally initiates a STORE operation after  $t_{DELAY}$ . An actual STORE cycle only begins if a WRITE to the SRAM took place since the last STORE or RECALL cycle. The  $\overline{HSB}$  pin has a very resistive pull up and is internally driven low to indicate a busy condition while the STORE (initiated by any means) is in progress. This pin should be externally pulled up if it is used to drive other inputs.

SRAM READ and WRITE operations that are in progress when  $\overline{HSB}$  is driven low by any means are given time to complete before the STORE operation is initiated. After  $\overline{HSB}$  goes low, the STK17T88 continues to allow SRAM operations for  $t_{DELAY}$ . During  $t_{DELAY}$ , multiple SRAM READ operations may take place. If a WRITE is in progress when  $\overline{HSB}$  is pulled low, it is allowed a time,  $t_{DELAY}$ , to complete. However, any SRAM WRITE cycles requested after  $\overline{HSB}$  goes low will be inhibited until  $\overline{HSB}$  returns high.

During any STORE operation, regardless of how it was initiated, the STK17T88 will continue to drive the  $\overline{HSB}$  pin low, releasing it only when the STORE is complete. Upon completion of the STORE operation, the STK17T88 will remain disabled until the  $\overline{HSB}$  pin returns high.

If  $\overline{HSB}$  is not used, it should be left unconnected.

### Hardware Recall (POWER UP)

During power up or after any low-power condition ( $V_{CC} < V_{SWITCH}$ ), an internal RECALL request will be latched. When  $V_{CC}$  once again exceeds the sense voltage of  $V_{SWITCH}$ , a RECALL cycle is automatically initiated and takes  $t_{HRECALL}$  to complete.

## Software STORE

Data can be transferred from the SRAM to the nonvolatile memory by a software address sequence. The STK17T88 software *STORE* cycle is initiated by executing sequential  $\bar{E}$  controlled READ cycles from six specific address locations in exact order. During the *STORE* cycle, previous data is erased and then the new data is programmed into the nonvolatile elements. Once a *STORE* cycle is initiated, further memory inputs and outputs are disabled until the cycle is completed.

To initiate the software *STORE* cycle, the following READ sequence must be performed:

1. Read address 0x0E38, Valid READ
2. Read address 0x31C7, Valid READ
3. Read address 0x03E0, Valid READ
4. Read address 0x3C1F, Valid READ
5. Read address 0x303F, Valid READ
6. Read address 0x0FC0, Initiate STORE cycle

Once the sixth address in the sequence has been entered, the *STORE* cycle commences and the chip is disabled. It is important that READ cycles and not WRITE cycles be used in the sequence. After the  $t_{STORE}$  cycle time has been fulfilled, the SRAM is again activated for READ and WRITE operation.

## Software RECALL

Data can be transferred from the nonvolatile memory to the SRAM by a software address sequence. A software *RECALL* cycle is initiated with a sequence of READ operations in a manner similar to the software *STORE* initiation. To initiate the *RECALL* cycle, the following sequence of  $\bar{E}$  controlled READ operations must be performed:

1. Read address 0x0E38, Valid READ
2. Read address 0x31C7, Valid READ
3. Read address 0x03E0, Valid READ
4. Read address 0x3C1F, Valid READ
5. Read address 0x303F, Valid READ
6. Read address 0x0C63, Initiate RECALL cycle

Internally, *RECALL* is a two-step procedure. First, the SRAM data is cleared, and second, the nonvolatile information is transferred into the SRAM cells. After the  $t_{RECALL}$  cycle time, the SRAM is again ready for READ or WRITE operations. The *RECALL* operation in no way alters the data in the nonvolatile storage elements.

## Data Protection

The STK17T88 protects data from corruption during low-voltage conditions by inhibiting all externally initiated STORE and WRITE operations. The low-voltage condition is detected when  $V_{CC} < V_{SWITCH}$ .

If the STK17T88 is in a WRITE mode (both  $\bar{E}$  and  $\bar{W}$  low) at power up, after a *RECALL*, or after a *STORE*, the WRITE is inhibited until a negative transition on  $\bar{E}$  or  $\bar{W}$  is detected. This protects against inadvertent writes during power up or brown out conditions.

## Noise Considerations

The STK17T88 is a high-speed memory and so must have a high-frequency bypass capacitor of 0.1  $\mu$ F connected between both  $V_{CC}$  pins and  $V_{SS}$  ground plane with no plane break to chip  $V_{SS}$ . Use leads and traces that are as short as possible. As with all high-speed CMOS ICs, careful routing of power, ground, and signals reduce circuit noise.

## Preventing AutoStore

Because of the use of nvSRAM to store critical RTC data, the AutoStore function can not be disabled on the STK17T88.

## Best Practices

nvSRAM products have been used effectively for over 15 years. While ease-of-use is one of the product's main system values, experience gained working with hundreds of applications has resulted in the following suggestions as best practices:

- The nonvolatile cells in an nvSRAM are programmed on the test floor during final test and quality assurance. Incoming inspection routines at customer or contract manufacturer's sites sometimes reprograms these values. Final NV patterns are typically repeating patterns of AA, 55, 00, FF, A5, or 5A. End product's firmware should not assume an NV array is in a set programmed state. Routines that check memory content values to determine first time system configuration, cold or warm boot status, etc. should always program a unique NV pattern (e.g., complex 4-byte pattern of 46 E6 49 53 hex or more random bytes) as part of the final system manufacturing test to ensure these system routines work consistently.
- Power up boot firmware routines should rewrite the nvSRAM into the desired state (autostore enabled, etc.). While the nvSRAM is shipped in a preset state, best practice is to again rewrite the nvSRAM into the desired state as a safeguard against events that might flip the bit inadvertently (program bugs, incoming inspection routines, etc.).
- The OSCEN bit in the Calibration register at 0x7FF8 should be set to 1 to preserve battery life when the system is in storage (see [Stopping and Starting the RTC Oscillator](#) on page 14).
- The  $V_{CAP}$  value specified in this datasheet includes a minimum and a maximum value size. Best practice is to meet this requirement and not exceed the max  $V_{CAP}$  value because the nvSRAM internal algorithm calculates  $V_{CAP}$  charge time based on this max  $V_{cap}$  value. Customers that want to use a larger  $V_{CAP}$  value to make sure there is extra store charge and store time should discuss their  $V_{cap}$  size selection with Cypress to understand any impact on the  $V_{CAP}$  voltage level at the end of a  $t_{RECALL}$  period.

## Real Time Clock

The clock registers maintain time up to 9,999 years in one-second increments. The user can set the time to any calendar time and the clock automatically keeps track of days of the week and month, leap years, and century transitions. There are eight registers dedicated to the clock functions which are used to set time with a write cycle and to read time during a read cycle. These registers contain the Time of Day in BCD format. Bits defined as “0” are currently not used and are reserved for future use by Cypress.

### Reading the Clock

The user should halt internal updates to the real time clock registers before reading clock data to prevent reading of data in transition. Stopping the internal register updates does not affect clock accuracy.

Write a “1” to the read bit “R” (in the Flags register at 0x7FF0) to capture the current time in holding registers. Clock updates do not restart until a “0” is written to the read bit. The RTC registers can now be read while the internal clock continues to run.

Within 20ms after a “0” is written to the read bit, all real time clock registers are simultaneously updated.

### Setting the Clock

Set the write bit “W” (in the Flags register at 0x7FF0) to a “1” enable the time to be set. The correct day, date and time can then be written into the real time clock registers in 24-hour BCD format. The time written is referred to as the “Base Time.” This value is stored in nonvolatile registers and used in calculation of the current time. Reset the write bit to “0” to transfer the time to the actual clock counters. The clock starts counting at the new base time.

### Backup Power

The RTC is intended to keep time even when system power is lost. When primary power,  $V_{CC}$ , drops below  $V_{SWITCH}$ , the real time clock switches to the backup power supply connected to either the  $V_{RTCcap}$  or  $V_{RTCbatt}$  pin.

The clock oscillator uses a maximum of 300 nanoamps at 2 volts to maximize the backup time available from the backup source.

You can power the real time clock with either a capacitor or a battery. Factors to be considered when choosing a backup power source include the expected duration of power outages and the cost and reliability trade-off of using a battery versus a capacitor.

If you select a capacitor power source, connect the capacitor to the  $V_{RTCcap}$  pin and leave the  $V_{RTCbatt}$  pin unconnected. Capacitor backup time values based on maximum current specs are shown below. Nominal times are approximately 3 times longer.

Capacitor Value	Backup Time
0.1 F	72 hours
0.47 F	14 days
1.0 F	30 days

A capacitor has the obvious advantage of being more reliable and not containing hazardous materials. The capacitor is recharged every time the power is turned on so that the real time clock continues to have the same backup time over years of operation

If you select a battery power source, connect the battery to the  $V_{RTCbatt}$  pin and leave the  $V_{RTCcap}$  pin unconnected. A 3V lithium is recommended for this application. The battery capacity should be chosen for the total anticipated cumulative down-time required over the life of the system.

The real time clock is designed with a diode internally connected to the  $V_{RTCbatt}$  pin. This prevents the battery from ever being charged by the circuit.

### Stopping and Starting the RTC Oscillator

The OSCEN bit in Calibration register at 0x7FF8 enables RTC oscillator operation. This bit is nonvolatile and shipped to customers in the “enabled” state (set to 0). OSCEN should be set to a 1 to preserve battery life while the system is in storage. This turns off the oscillator circuit extending the battery life. If the OSCEN bit goes from disabled to enabled, it typically takes 5 seconds (10 seconds max) for the oscillator to start.

The STK17T88 has the ability to detect oscillator failure due to loss of backup power. The failure is recorded by the OSCF (Oscillator Failed bit) of the Flags register (at address 0x7FF0). When the device is powered on ( $V_{CC}$  goes above  $V_{SWITCH}$ ) the OSCEN bit is checked for “enabled” status. If the OSCEN bit is enabled and the oscillator is not active within 5 ms, the OSCF bit is set. The user should check for this condition and then write a 0 to clear the flag. When the OSCF flag bit, the real time clock registers are reset to the “Base Time” (see the section [Setting the Clock](#) on page 14, the value last written to the real time clock registers.

The value of OSCF should be reset to 0 when the real time clock registers are written for the first time. This initializes the state of this bit since it may have become set when the system was first powered on.

To reset OSCF, set the write bit “W” (in the Flags register at 0x7FF0) to a “1” to enable writes to the Flags register. Write a “0” to the OSCF bit and then reset the write bit to “0” to disable writes.

### Calibrating The Clock

The RTC is driven by a quartz controlled oscillator with a nominal frequency of 32.768 KHz. Clock accuracy depends on the quality of the crystal specified (usually 35 ppm at 25 C). This error could equate to 1.53 minutes gain or loss per month. The STK17T88 employs a calibration circuit that can improve the accuracy to +1/-2 ppm at 25 C. The calibration circuit adds or subtracts counts from the oscillator divider circuit.

The number of time pulses added or subtracted depends upon the value loaded into the five calibration bits found in Calibration register (at 0x7FF8). Adding counts speeds the clock up; subtracting counts slows the clock down. The Calibration bits occupy the five lower order bits of the register. These bits can be set to represent any value between 0 and 31 in binary form. Bit D5 is a Sign bit, where a “1” indicates positive calibration and a “0” indicates negative calibration. Calibration occurs during a 64 minute period. The first 62 minutes in the cycle may, once per



minute, have one second either shortened by 128 or lengthened by 256 oscillator cycles.

If a binary “1” is loaded into the register, only the first 2 minutes of the 64 minute cycle is modified; if a binary 6 is loaded, the first 12 are affected, and so on. Therefore each calibration step has the effect of adding 512 or subtracting 256 oscillator cycles for every 125,829,120 actual oscillator cycles. That is +4.068 or -2.034 ppm of adjustment per calibration step in the Calibration register.

The calibration register value is determined during system test by setting the CAL bit in the Flags register (at 0x7FF0) to 1. This causes the INT pin to toggle at a nominal 512 Hz. This frequency can be measured with a frequency counter. Any deviation measured from the 512 Hz indicates the degree and direction of the required correction. For example, a reading of 512.01024 Hz would indicate a +20 ppm error, requiring a -10 (001010) to be loaded into the Calibration register. Note that setting or changing the calibration register does not affect the frequency test output frequency.

To set or clear CAL, set the write bit “W” (in the Flags register at 0x7FF0) to a “1” to enable writes to the Flags register. Write a value to CAL and then reset the write bit to “0” to disable writes.

The default Calibration register value from the factory is 00h. The user calibration value loaded is retained during a power loss.

### Alarm

The alarm function compares a user-programmed alarm time/date (stored in registers 0x7FF1-5) with the real time clock time-of-day/date values. When a match occurs, the alarm flag (AF) is set and an interrupt is generated if the alarm interrupt is enabled. The alarm flag is automatically reset when the Flags register is read.

Each of the alarm registers has a match bit as its MSB. Setting the match bit to a 1 disables this alarm register from the alarm comparison. When the match bit is 0, the alarm register is compared with the equivalent real time clock register. Using the match bits, an alarm can occur as specifically as one particular second on one day of the month or as frequently as once per minute.

**Note** The product requires the match bit for seconds (0x7FF2, bit D7) be set to 0 for proper operation of the Alarm Flag and Interrupt.

The alarm value should be initialized on power up by software since the alarm registers are not nonvolatile.

To set or clear the Alarm registers, set the write bit “W” (in the Flags register at 0x7FF0) to a “1” to enable writes to the Alarm registers. Write an alarm value to the alarm registers and then reset the write bit to “0” to disable writes.

### Watchdog Timer

The watchdog timer is designed to interrupt or reset the processor should its program get hung in a loop and not respond in a timely manner. The software must reload the watchdog timer before it counts down to zero to prevent this interrupt or reset.

The watchdog timer is a free-running-down counter that uses the 32Hz clock (31.25 ms) derived from the crystal oscillator. The watchdog timer function does not operate unless the oscillator is running.

The watchdog counter is loaded with a starting value from the load register and then counts down to zero, setting the watchdog flag (WDF) and generating an interrupt if the watchdog interrupt is enabled. The watchdog flag bit is reset when the Flags register is read. The operating software would normally reload the counter by setting the watchdog strobe bit (WDS) to 1 within the timing interval programmed into the load register.

To use the watchdog timer to reset the processor on timeout, the INT is tied to processor master reset and Interrupt register is programmed to 24h to enable interrupts to pulse the reset pin on timeout.

To load the watchdog timer, set a new value into the load register by writing a “0” to the watchdog write bit (WDW) of the watchdog register (at 0x7FF7). Then load a new value into the load register. Once the new value is loaded, the watchdog write bit is then set to 1 to disable watchdog writes. The watchdog strobe bit (WDS) is set to 1 to load this value into the watchdog timer. Note: Setting the load register to zero disables the watchdog timer function.

The system software should initialize the watchdog load register on power up to the desired value since the register is not nonvolatile.

### Power Monitor

The STK17T88 provides a power monitor function. The power monitor is based on an internal band-gap reference circuit that compares the  $V_{CC}$  voltage to  $V_{SWITCH}$ .

When the power supply drops below  $V_{SWITCH}$ , the real time clock circuit is switched to the backup supply (battery or capacitor).

When operating from the backup source, no data may be read or written and the clock functions are not available to the user. The clock continues to operate in the background. Updated clock data is available to the user  $t_{HRECALL}$  delay after  $V_{CC}$  has been restored to the device.

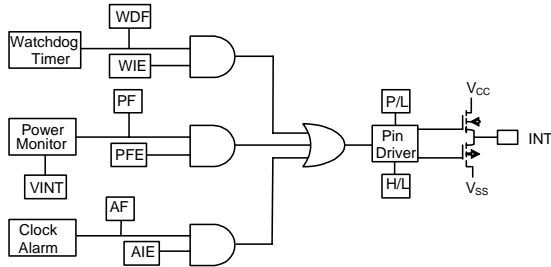
When the power is lost, the PF flag in the Flags register is set to indicate the power failure and an interrupt is generated if the power fail interrupt is enabled (interrupt register=20h). The INT line would normally be tied to the processor master reset input to perform power-off reset.

### Interrupts

The STK17T88 has a Flags register, Interrupt register, and interrupt logic that can interrupt the microcontroller or general a power up master reset signal. There are three potential interrupt sources: the watchdog timer, the power monitor, and the clock alarm. Each can be individually enabled to drive the INT pin by setting the appropriate bit in the Interrupt register. In addition, each has an associated flag bit in the Flags register that the host processor can read to determine the interrupt source. Two bits in the interrupt register determine the operation of the INT pin driver.

Figure 15 is a functional diagram of the interrupt logic.

**Figure 15. Interrupt Block Diagram**



**Interrupt Register**

Watchdog Interrupt Enable (WIE). When set to 1, the watchdog timer drives the INT pin when a watchdog time-out occurs. When WIE is set to 0, the watchdog time-out only sets the WDF flag bit.

Alarm Interrupt Enable (AIE). When set to 1, the INT pin is driven when an alarm match occurs. When set to 0, the alarm match only sets the AF flag bit.

Power Fail Interrupt Enable (PFE). When set to 1, the INT pin is driven by a power fail signal from the power monitor. When set to 0, only the PF flag is set.

High/Low (H/L). When set to a 1, the INT pin is active high and the driver mode is push-pull. The INT pin can drive high only when  $V_{CC} > V_{SWITCH}$ . When set to a 0, the INT pin is active low and the drive mode is open-drain. The active low (open drain) output is maintained even when power is lost.

Pulse/Level (P/L). When set to a 1, the INT pin is driven for approximately 200 ms when the interrupt occurs. The pulse is reset when the Flags register is read. When P/L is set to a 0, the INT pin is driven high or low (determined by H/L) until the Flags register is read.

The Interrupt register is loaded with the default value 00h at the factory. The user should configure the Interrupt register to the value desired for their desired mode of operation. Once configured, the value is retained during power failures.

**Flags Register**

The Flags register has three flag bits: WDF, AF, and PF. These flags are set by the watchdog time-out, alarm match, or power fail monitor respectively. The processor can either poll this register or enable the interrupts to be informed when a flag is set. The flags are automatically reset once the register is read.

The Flags register is automatically loaded with the value 00h on power up (with the exception of the OSCF bit).



RTC Register Map

Register	BCD Format Data								Function / Range
	D7	D6	D5	D4	D3	D2	D1	D0	
0x7FFF	10s Years				Years				Years: 00-99
0x7FFE	0	0	0	10s Months	Months				Months: 01-12
0x7FFD	0	0	10s Day of Month		Day of Month				Day of Month: 01-31
0x7FFC	0	0	0	0	0	Day of Week			Day of week: 01-07
0x7FFB	0	0	10s Hours		Hours				Hours: 00-23
0x7FFA	0	10s Minutes			Minutes				Minutes: 00-59
0x7FF9	0	10s Seconds			Seconds				Seconds: 00-59
0x7FF8	OSCN [0]	0	Cal Sign	Calibration [00000]					Calibration values*
0x7FF7	WDS	WDW	WDT						Watchdog*
0x7FF6	WIE[0]	AIE[0]	PFE[0]	0	H/L [1]	P/L [0]	0	0	Interrupts*
0x7FF5	M	0	10s Alarm Date		Alarm Day				Alarm, Day of Month: 01-31
0x7FF4	M	0	10s Alarm Hours		Alarm Hours				Alarm, hours: 00-23
0x7FF3	M	10 Alarm Minutes			Alarm Minutes				Alarm, minutes: 00-59
0x7FF2	M	10 Alarm Seconds			Alarm Seconds				Alarm, seconds: 00-59
0x7FF1	10s Centuries				Centuries				Centuries: 00-99
0x7FF0	WDF	AF	PF	OSCF	0	CAL[0]	W[0]	R[0]	Flags*

\*A binary value, not a BCD value.

0 - Not implemented, reserved for future use.

Default Settings of nonvolatile Calibration and Interrupt registers from factory

Calibration Register=00h

Interrupt Register=00h

The User should configure to the desired value at startup or during operation and the value is then retained during a power failure.

[ ] designates values shipped from the factory. See [Stopping and Starting the RTC Oscillator](#) on page 14.

**Register Map Detail**

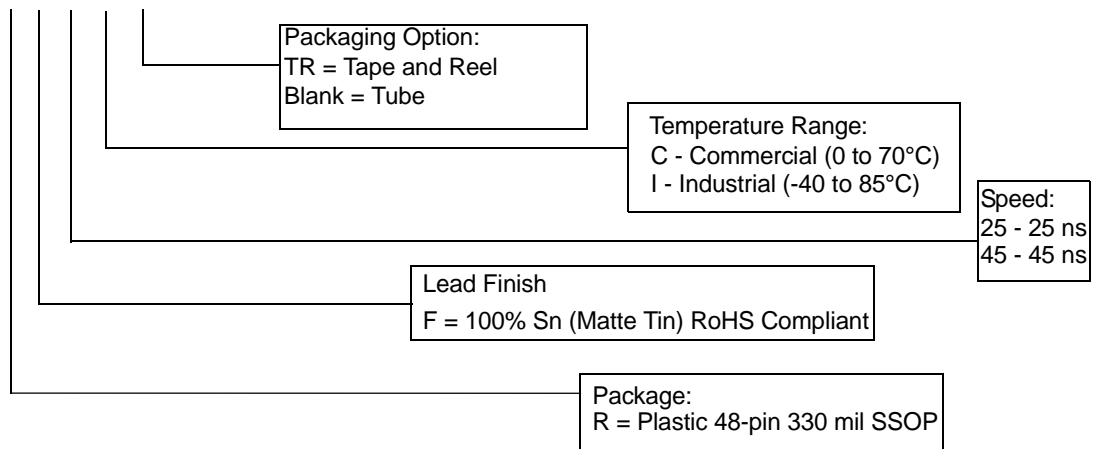
0x7FFF	Real Time Clock – Years							
	D7	D6	D5	D4	D3	D2	D1	D0
	10s Years				Years			
	Contains the lower two BCD digits of the year. Lower nibble contains the value for years; upper nibble contains the value for 10s of years. Each nibble operates from 0 to 9. The range for the register is 0-99.							
0x7FFE	Real Time Clock – Months							
	D7	D6	D5	D4	D3	D2	D1	D0
	0	0	0	10s Month	Months			
	Contains the BCD digits of the month. Lower nibble contains the lower digit and operates from 0 to 9; upper nibble (one bit) contains the upper digit and operates from 0 to 1. The range for the register is 1-12.							
0x7FFD	Real Time Clock – Date							
	D7	D6	D5	D4	D3	D2	D1	D0
	0	0	10s Day of month		Day of month			
	Contains the BCD digits for the date of the month. Lower nibble contains the lower digit and operates from 0 to 9; upper nibble contains the upper digit and operates from 0 to 3. The range for the register is 1-31. Leap years are automatically adjusted for.							
0x7FFC	Real Time Clock – Day							
	D7	D6	D5	D4	D3	D2	D1	D0
	0	0	0	0	0	Day of week		
	Lower nibble contains a value that correlates to day of the week. Day of the week is a ring counter that counts from 1 to 7 then returns to 1. The user must assign meaning to the day value, as the day is not integrated with the date.							
0x7FFB	Real Time Clock – Hours							
	D7	D6	D5	D4	D3	D2	D1	D0
	0	0	10s Hours		Hours			
	Contains the BCD value of hours in 24 hour format. Lower nibble contains the lower digit and operates from 0 to 9; upper nibble (two bits) contains the upper digit and operates from 0 to 2. The range for the register is 0-23.							
0x7FFA	Real Time Clock – Minutes							
	D7	D6	D5	D4	D3	D2	D1	D0
	0	10s Minutes			Minutes			
	Contains the BCD value of minutes. Lower nibble contains the lower digit and operates from 0 to 9; upper nibble contains the upper minutes digit and operates from 0 to 5. The range for the register is 0-59.							
0x7FF9	Real Time Clock – Seconds							
	D7	D6	D5	D4	D3	D2	D1	D0
	0	10s Seconds			Seconds			
	Contains the BCD value of seconds. Lower nibble contains the lower digit and operates from 0 to 9; upper nibble contains the upper digit and operates from 0 to 5. The range for the register is 0-59.							
0x7FF8	Calibration							
	D7	D6	D5	D4	D3	D2	D1	D0
	OSCEN	0	Calibration Sign	Calibration				
OSCEN	Oscillator Enable. When set to 1, the oscillator is disabled. When set to 0, the oscillator is enabled. Disabling the oscillator saves battery/capacitor power during storage.							
Calibration Sign	Determines if the calibration adjustment is applied as an addition to or as a subtraction from the time-base.							
Calibration	These five bits control the calibration of the clock.							
0x7FF7	Watchdog Timer							
	D7	D6	D5	D4	D3	D2	D1	D0
	WDS	WDW	WDT					
WDS	Watchdog Strobe. Setting this bit to 1 reloads and restarts the watchdog timer. The bit is cleared automatically once the watchdog timer is reset. The WDS bit is write only. Reading it always will return a 0.							

**Register Map Detail** (continued)

WDW	Watchdog Write Enable. Set this bit to 1 to disable writing of the watchdog time-out value (WDT5-WDT0). This allows the user to strobe the watchdog without disturbing the time-out value. Setting this bit to 0 allows bits 5-0 to be written.							
WDT	Watchdog time-out selection. The watchdog timer interval is selected by the 6-bit value in this register. It represents a multiplier of the 32 Hz count (31.25 ms). The range or time-out values is 31.25 ms (a setting of 1) to 2 seconds (setting of 3Fh). Setting the watchdog timer register to 0 disables the timer. These bits can be written only if the WDW bit was cleared to 0 on a previous cycle.							
<b>0x7FF6</b>	<b>Interrupt</b>							
	<b>D7</b>	<b>D6</b>	<b>D5</b>	<b>D4</b>	<b>D3</b>	<b>D2</b>	<b>D1</b>	<b>D0</b>
	WIE	AIE	PFIE	ABE	H/L	P/L	0	0
WIE	Watchdog Interrupt Enable. When set to 1 and a watchdog time-out occurs, the watchdog timer drives the INT pin and sets the WDF flag. When set to 0, the watchdog time-out only sets the WDF flag.							
AIE	Alarm Interrupt Enable. When set to 1, the alarm match drives the INT pin and sets the AF flag. When set to 0, the alarm match only sets the AF flag.							
PFIE	Power-Fail Enable. When set to 1, a power failure drives the INT pin and sets the PF flag. When set to 0, a power failure only sets the PF flag.							
0	Reserved for Future Use							
H/L	High/Low. When set to a 1, the INT pin is driven active high. When set to 0, the INT pin is open drain, active low.							
P/L	Pulse/Level. When set to a 1, the INT pin is driven active (determined by H/L) by an interrupt source for approximately 200 ms. When set to a 0, the INT pin is driven to an active level (as set by H/L) until the Flags register is read.							
<b>0x7FF5</b>	<b>Alarm – Day</b>							
	<b>D7</b>	<b>D6</b>	<b>D5</b>	<b>D4</b>	<b>D3</b>	<b>D2</b>	<b>D1</b>	<b>D0</b>
	M	0	10s Alarm Date		Alarm Date			
	Contains the alarm value for the date of the month and the mask bit to select or deselect the date value.							
M	Match. Setting this bit to 0 causes the date value to be used in the alarm match. Setting this bit to 1 causes the match circuit to ignore the date value.							
<b>0x7FF4</b>	<b>Alarm – Hours</b>							
	<b>D7</b>	<b>D6</b>	<b>D5</b>	<b>D4</b>	<b>D3</b>	<b>D2</b>	<b>D1</b>	<b>D0</b>
	M	0	10s Alarm Hours		Alarm Hours			
	Contains the alarm value for the hours and the mask bit to select or deselect the hours value.							
M	Match. Setting this bit to 0 causes the hours value to be used in the alarm match. Setting this bit to 1 causes the match circuit to ignore the hours value.							
<b>0x7FF3</b>	<b>Alarm – Minutes</b>							
	<b>D7</b>	<b>D6</b>	<b>D5</b>	<b>D4</b>	<b>D3</b>	<b>D2</b>	<b>D1</b>	<b>D0</b>
	M	10s Alarm Minutes			Alarm Minutes			
	Contains the alarm value for the minutes and the mask bit to select or deselect the minutes value.							
M	Match. Setting this bit to 0 causes the minutes value to be used in the alarm match. Setting this bit to 1 causes the match circuit to ignore the minutes value.							
<b>0x7FF2</b>	<b>Alarm – Seconds</b>							
	<b>D7</b>	<b>D6</b>	<b>D5</b>	<b>D4</b>	<b>D3</b>	<b>D2</b>	<b>D1</b>	<b>D0</b>
	M	10s Alarm Seconds			Alarm Seconds			
	Contains the alarm value for the seconds and the mask bit to select or deselect the seconds' value.							
M	Match. Setting this bit to 0 causes the seconds' value to be used in the alarm match. Setting this bit to 1 causes the match circuit to ignore the seconds value.							
<b>0x7FF1</b>	<b>Real Time Clock – Centuries</b>							
	<b>10s Centuries</b>				<b>Centuries</b>			
	Contains the BCD value of Centuries. Lower nibble contains the lower digit and operates from 0 to 9; upper nibble contains the upper centuries digit and operates from 0 to 9. The range for the register is 0-99 centuries.							

**Register Map Detail** (continued)

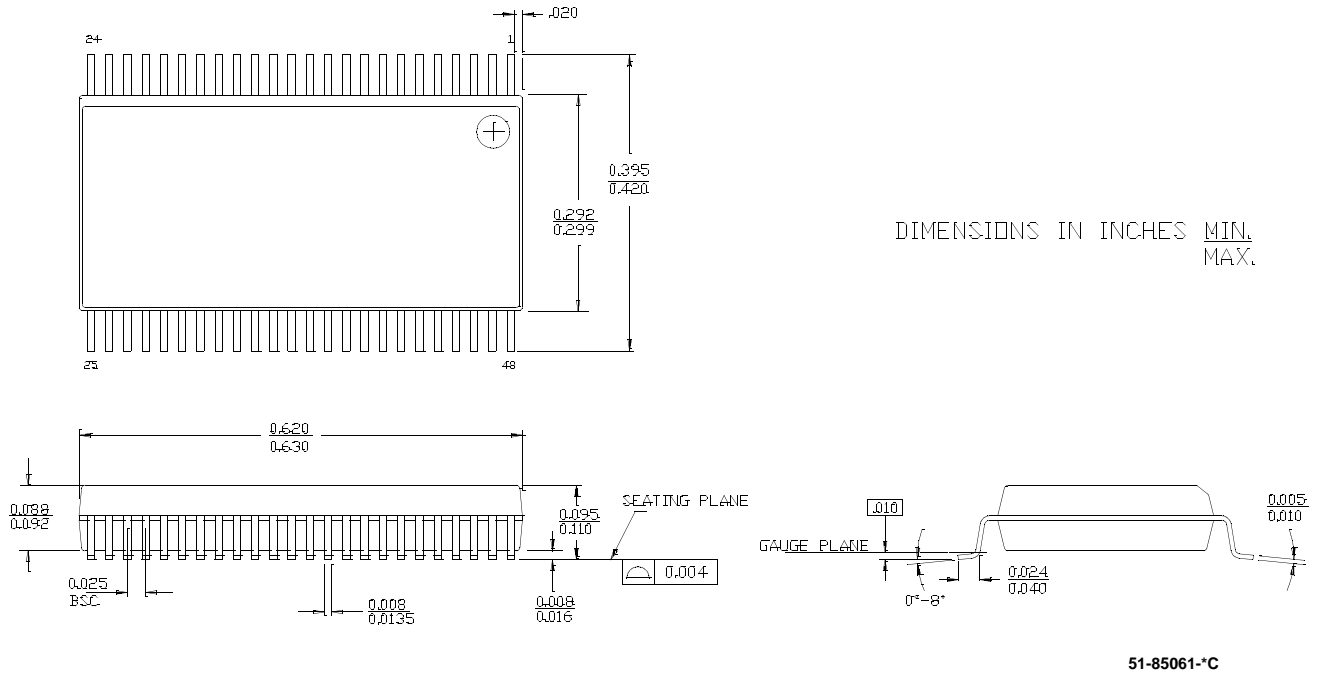
0x7FF0	Flags							
	D7	D6	D5	D4	D3	D2	D1	D0
	WDF	AF	PF	OSCF	0	CAL	W	R
WDF	Watchdog Timer Flag. This read-only bit is set to 1 when the watchdog timer is allowed to reach 0 without being reset by the user. It is cleared to 0 when the Flags register is read or on power up							
AF	Alarm Flag. This read-only bit is set to 1 when the time and date match the values stored in the alarm registers with the match bits = 0. It is cleared when the Flags register is read or on power up							
PF	Power-fail Flag. This read-only bit is set to 1 when power falls below the power-fail threshold $V_{SWITCH}$ . It is cleared to 0 when the Flags register is read or on power up.							
OSCF	Oscillator Fail Flag. Set to 1 on power up only if the oscillator is enabled and not running in the first 5ms of operation. This indicates that the RTC backup power failed and the clock value is no longer valid. The user must reset this bit to 0 to clear this condition.							
CAL	Calibration Mode. When set to 1, a 512Hz square wave is output on the INT pin. When set to 0, the INT pin resumes normal operation. This bit defaults to 0 (disabled) on power up.							
W	Write Time. Setting the W bit to 1 freezes updates of the RTC registers. The user can then write to the RTC registers, Alarm registers, Calibration register, Interrupt register and Flags register. Setting the W bit to 0 disables writes to the registers and causes the contents of the real time clock registers to be transferred to the timekeeping counters if the time has changed (a new base time is loaded). The bit defaults to 0 on power up.							
R	Read Time. Setting the R bit to 1 captures the current time in holding registers so that clock updates are not during the reading process. Set the R bit to 0 to enable the holding register to resume clock updates. The bit defaults to 0 on power up.							

**Commercial and Industrial Ordering Information**
**STK17T88 - R F 45 I TR**

**Ordering Codes**

Ordering Code	Description	Access Times (ns)	Temperature
STK17T88-RF25	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	25	Commercial
STK17T88-RF45	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	45	Commercial
STK17T88-RF25TR	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	25	Commercial
STK17T88-RF45TR	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	45	Commercial
STK17T88-RF25I	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	25	Industrial
STK17T88-RF45I	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	45	Industrial
STK17T88-RF25ITR	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	25	Industrial
STK17T88-RF45ITR	3.3V 32Kx8 AutoStore nvSRAM+RTC SSOP48-300	45	Industrial

Package Diagram

Figure 16. 48-Pin SSOP (51-85061)



## Document History Page

Document Title: STK17T88 32K x 8 AutoStore™ nvSRAM with Real-Time Clock Document Number: 001- 52040				
Rev	ECN No.	Orig. of Change	Submission Date	Description of change
**	2668660	GVCH/PYRS	03/04/2009	New data sheet
*A	2675319	GVCH	03/17/2009	Corrected typo on page 1 in 'Description' section: changed 256KB to 256Kb.

## Sales, Solutions, and Legal Information

### Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer’s representatives, and distributors. To find the office closest to you, visit us at [cypress.com/sales](http://cypress.com/sales).

### Products

PSoC	<a href="http://psoc.cypress.com">psoc.cypress.com</a>
Clocks & Buffers	<a href="http://clocks.cypress.com">clocks.cypress.com</a>
Wireless	<a href="http://wireless.cypress.com">wireless.cypress.com</a>
Memories	<a href="http://memory.cypress.com">memory.cypress.com</a>
Image Sensors	<a href="http://image.cypress.com">image.cypress.com</a>

### PSoC Solutions

General	<a href="http://psoc.cypress.com/solutions">psoc.cypress.com/solutions</a>
Low Power/Low Voltage	<a href="http://psoc.cypress.com/low-power">psoc.cypress.com/low-power</a>
Precision Analog	<a href="http://psoc.cypress.com/precision-analog">psoc.cypress.com/precision-analog</a>
LCD Drive	<a href="http://psoc.cypress.com/lcd-drive">psoc.cypress.com/lcd-drive</a>
CAN 2.0b	<a href="http://psoc.cypress.com/can">psoc.cypress.com/can</a>
USB	<a href="http://psoc.cypress.com/usb">psoc.cypress.com/usb</a>

© Cypress Semiconductor Corporation, 2009. The information contained herein is subject to change without notice. Cypress Semiconductor Corporation assumes no responsibility for the use of any circuitry other than circuitry embodied in a Cypress product. Nor does it convey or imply any license under patent or other rights. Cypress products are not warranted nor intended to be used for medical, life support, life saving, critical control or safety applications, unless pursuant to an express written agreement with Cypress. Furthermore, Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress products in life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Any Source Code (software and/or firmware) is owned by Cypress Semiconductor Corporation (Cypress) and is protected by and subject to worldwide patent protection (United States and foreign), United States copyright laws and international treaty provisions. Cypress hereby grants to licensee a personal, non-exclusive, non-transferable license to copy, use, modify, create derivative works of, and compile the Cypress Source Code and derivative works for the sole purpose of creating custom software and or firmware in support of licensee product to be used only in conjunction with a Cypress integrated circuit as specified in the applicable agreement. Any reproduction, modification, translation, compilation, or representation of this Source Code except as specified above is prohibited without the express written permission of Cypress.

Disclaimer: CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. Cypress reserves the right to make changes without further notice to the materials described herein. Cypress does not assume any liability arising out of the application or use of any product or circuit described herein. Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress’ product in a life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Use may be limited by and subject to the applicable Cypress software license agreement.