

MARCH 2010

### **GENERAL DESCRIPTION**

The SP336E is a monolithic serial multi-transceiver device that contains both RS-232 and RS-485/RS-422 line drivers and receivers. The configuration of the SP336E can be reconfigured into eight operating modes including RS-232 only (4TX/4RX), RS-485/ RS-422 only (2TX/2RX) full or half duplex, two RS-232/RS-485 mixed modes. two shutdown modes and a diagnostic loop-back mode. Modes may be selected at any time by changing the logic state of the three MODE pins. The device can implement a dualmode serial port, mixed mode ports or as an interface signal translator. The Exar charge pumps deliver true RS-232 driver output voltages from a single power supply at either 3.3V or 5V. The SP336E requires only four 0.1µF capacitors for charge pump. A slew rate control pin configures driver outputs for either high data rate or slew-controlled data rates. Slewcontrolled outputs minimize problems with reflections and ringing on long or un-terminated cables. All RS-485 receivers or transceivers feature high impedance which allow up to 256 transceivers on a shared bus. When configured in RS-485/RS-422 mode, each driver may be individually enabled or put into tri-state, simplifying use on shared buses or bidirectional communication. All receivers have advanced failsafe protection to prevent oscillation when inputs are unconnected. In RS-232 mode each receiver input has a 5k ohm pull-down to ground. Differential Receivers will default to output logic 1 if inputs are floating, shorted or open but terminated. All driver outputs and receiver inputs are protected against ESD strikes up to +/-15,000 volts.

#### FEATURES

- 3.3V or 5V Single Supply Operation
- Robust +/-15kV ESD Protection (IEC 61000-4-2 Air Gap)

SP336E

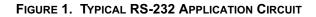
REV. 1.0.0

- Software Selectable Mode Selection
- Up to 4 Drivers, 4 Receivers RS-232/V.28
- Up to 2 Drivers, 2 Receivers RS-485/RS-422
  - Full or Half Duplex Configurations
  - 1/8th Unit Load, up to 256 receivers on bus
- Mixed RS-232/RS-485 modes
- Pin Programmable Slew Rate for Reduced EMI
- RS-485 Advanced Failsafe on Open, Short or Terminated Lines
- Diagnostic Loop-Back Function
- 28 Pin SOIC or TSSOP Packaging

#### TYPICAL APPLICATIONS

- Factory Automation Equipment
- Security Networks
- Industrial/Process Control Networks
- Point-Of-Sales Equipment
- Gaming Machines
- Serial Protocol Translators (ex. RS-232 to RS-485/ RS-422)
- Embedded Industrial PC's
- Building Environmental Control Systems (ex. HVAC)
- Cable Repeaters / Port Extenders / Hubs





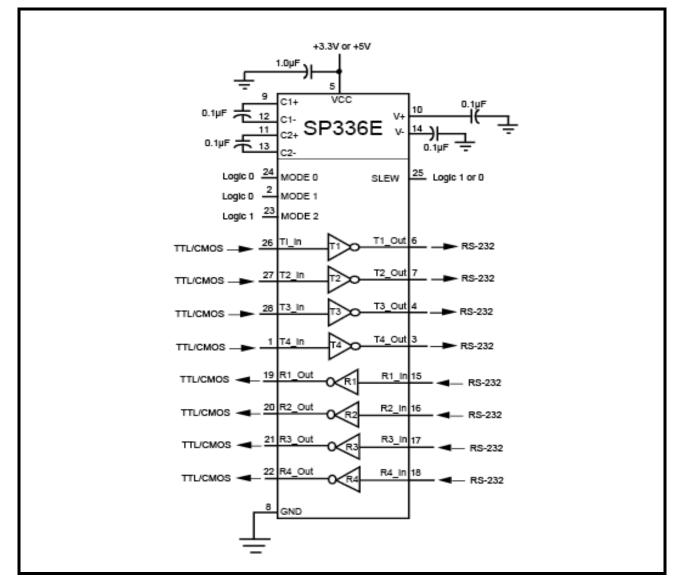
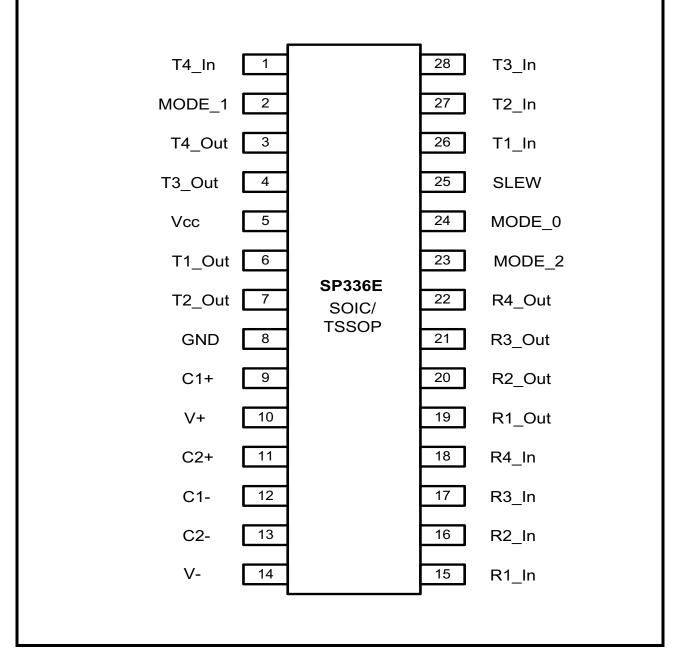




FIGURE 2. PIN OUT ASSIGNMENT

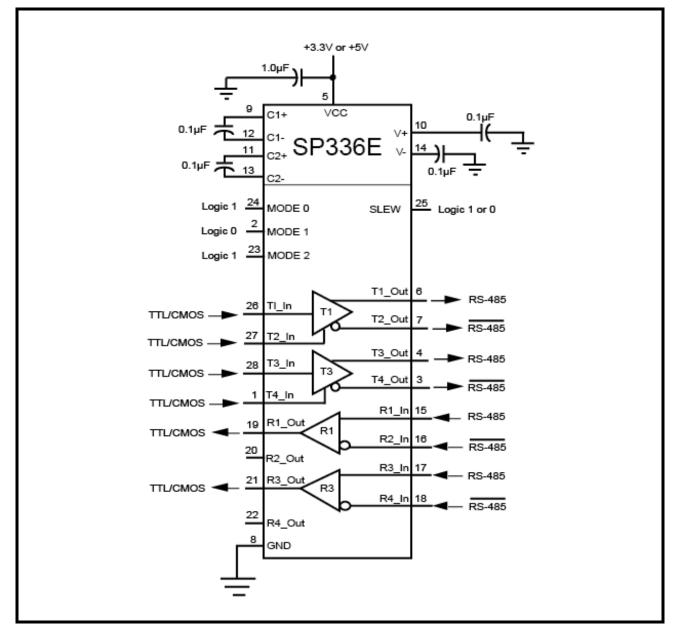


### **ORDERING INFORMATION**

PART NUMBER	Package	Operating Temperature Range	DEVICE STATUS
SP336ECT-L	28-pin SOIC-W	0°C to +70°C	Active
SP336ECY-L	28-pin TSSOP	0°C to +70°C	Active
SP336EET-L	28-pin SOIC-W	-40°C to +85°C	Active
SP336EEY-L	28-pin TSSOP	-40°C to +85°C	Active



#### FIGURE 3. TYPICAL RS-485 APPLICATION CIRCUIT





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SP336E

## **PIN DESCRIPTIONS**

## **Pin Assignments**

PIN NUMBER	PIN NAME	Түре		DESCRIPTION				
		ITPE	SINGLE ENDED	SINGLE ENDED FULL-DUPLEX H				
1	T4_In	I	T4 Driver TTL input.	T3 Driver Enable Active High.	T3 Driver Enable Active High, R3 Enable Active Low.			
2	Mode_1	I		Mode Configuration pin 1				
3	T4_Out	0	T4 Driver Output.	T3(A) Output.	T3(A) Output, R3(A) Input.			
4	T3_Out	0	T3 Driver Output.	T3(B) Output.	T3(B) Output, R3(B) Input.			
5	Vcc	Pwr		Power Supply Voltage.				
6	T1_Out	0	T1 Driver Output.	T1(A) Output.	T1(A) Output, R1(A) Input.			
7	T2_Out	0	T2 Driver Output.	T1(B) Output.	T1(B) Output, R1(B) Input.			
8	GND	Pwr	Ground.	Ground.				
9	C1+	Pmp	Positive	terminal of positive flying	capacitor.			
10	V+	Pmp		Vdd storage capacitor.				
11	C2+	Pmp	Positive t	Positive terminal of negative flying capacitor.				
12	C1-	Pmp	Negative	terminal of positive flying	capacitor.			
13	C2-	Pmp	Negative	terminal of negative flying	g capacitor.			
14	V-	Pmp		Vss storage capacitor.				
15	R1_In		R1 Receiver Input.	R1(A) Receiver Input.	High Impedance.			
16	R2_In	I	R2 Receiver Input.	R1(B) Receiver Input.	R2 Receiver Input.			
17	R3_In	I	R3 Receiver Input.	R3(A) Receiver Input.	High Impedance.			
18	R4_In	I	R4 Receiver Input.	R3(B) Receiver Input.	R4 Receiver Input.			
19	R1_Out	I	R1 Receiver Output.					
20	R2_Out	I	R2 Receiver Output. High Impedance. R2 Receiver Output.					
21	R3_Out		R3 Receiver Output.					
22	R4_Out		R4 Receiver Output.	High Impedance.	R4 Receiver Output.			
23	Mode_2	I	Mode Configuration pin 2.					
24	Mode_0	I	Mode Configuration pin 0.					
25	SLEW	I	Slew Rate Control. Logic Low input will limit driver slew from either RS-232 or RS-485 to 250kbps.					
26	T1_ln	I	T1 Driver Input.					



## 3.3V - 5V PROGRAMMABLE RS-232/RS-485/RS-422 SERIAL TRANSCEIVER

**Pin Assignments** 

PIN NUMBER	Pin Name	Түре	DESCRIPTION						DESCRIPTION			
TINTOMBER			SINGLE ENDED	FULL-DUPLEX	HALF-DUPLEX							
27	T2_ln	I	T2 Driver Input.	T1 Driver Enable Active High.	T1 Driver Enable Active High and R1 Receiver Enable Active Low.							
28	T3_ln	I	T3 Driver Input.									

Pin type: I=Input, O=Output, Pwr=Power supply, Pmp = Charge pump.



SP336E

## **MODE CONFIGURATION**

OPERATION:	RS-232 Mode	MIXED-PROTOCOL FULL DUPLEX		
	4T/4R RS-232	2T/2R RS-232 & 1T/1R RS-485		
Mode (M0, M1, M2)	001	011		
	26 T1 6	26 T1 6		
	27 7	27 T2 7		
	28 73 4			
	1 3	1		
	19 R1 15	19 R1 15		
	20	20 16		
	21 R3 17	21		
	22	22 —		

# EXAR Powering Connectivity REV. 1.0.0

## 3.3V - 5V PROGRAMMABLE RS-232/RS-485/RS-422 SERIAL TRANSCEIVER

# MODE CONFIGURATION (CONTINUED)

OPERATION:	LOW POWER SHUTDOWN		RS-485/RS-422 FULL DUPLEX		
	ALL I/O AT HIGH IMPEDANCE		2T/2R RS-485		
Mode (M0, M1, M2)	111		101		
Mode (M0, M1, M2)	111 26 - 27 - 28 - 1 - 19 - 20 - 21 -	- 6 - 7 - 4 - 3 - 15 - 16 - 17	101 $26$ $27$ $28$ $13$ $4$ $3$ $1$ $19$ $R1$ $15$ $16$ $20$ $21$ $R3$ $17$		
	22 —	- 18	22 — 18 22 —		



## MODE CONFIGURATION (CONTINUED)

OPERATION:	LOOP-BACK TXIN TO RXOUT	MIXED-PROTOCOL HALF DUPLEX		
	<b>TXOUT AND RXIN HIGH IMPEDANCE</b>	2T/3R RS-232 & 1T/1R RS-485		
Mode (M0, M1, M2)	000	010		
	$26 \qquad \boxed{1} \qquad 6$ $27 \qquad \boxed{1} \qquad 7$ $28 \qquad \boxed{1} \qquad 4$ $1 \qquad \boxed{1} \qquad \boxed{1} \qquad 3$ $19 \qquad \boxed{R1} \qquad 15$ $20 \qquad \boxed{R2} \qquad 16$ $21 \qquad \boxed{R3} \qquad 17$ $22 \qquad \boxed{R4} \qquad 18$	$26 \qquad 1 \qquad 6$ $27 \qquad 28 \qquad 3$ $1 \qquad 21 \qquad 8 \qquad 3$ $19 \qquad R1 \qquad 15$ $20 \qquad R2 \qquad 16$ $17 \qquad 22 \qquad R4 \qquad 18$		



# MODE CONFIGURATION (CONTINUED)

Mode (M0, M1, M2)	Drivers at High Impedance 110		4T/2R RS-485 & 2R RS-232
Mode (M0, M1, M2)	110		
			100
26 27 28 1 19 20 21 22		- 6 - 7 - 4 - 3 - 15 - 16 - 17 - 18	100 $26$ $27$ $19$ $R1$ $6$ $7$ $28$ $1$ $21$ $R3$ $4$ $3$ $20$ $R2$ $16$ $22$ $R4$ $18$



## **ABSOLUTE MAXIMUM RATINGS**

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections to the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability and cause permanent damage to the device.

Supply Voltage V <sub>CC</sub>	+6.0V
Receiver Input V <sub>IN</sub> (DC Input Voltage)	-15V to +15V
Input Voltage at TTL input Pins	-0.3V to Vcc + 0.5V
Driver Output Voltage (from Ground)	-7.5V to +12.5V
Short Circuit Duration, TXout to GND	Continuous
Storage Temperature Range	-65°C to + 150°C
Lead Temperature (soldering, 10s)	+300°C
Power Dissipation 28-pin SOIC-W (derate 17mW/°C above +70°C)	938mW
Power Dissipation 28-pin TSSOP (derate 12mW/°C above +70°C)	657mW

#### CAUTION:

ESD (Electrostatic Discharge) sensitive device. Permanent damage may occur on unconnected devices subject to high energy electrostatic fields. Unused devices must be stored in conductive foam or shunts. Personnel should be properly grounded prior to handling this device. The protective foam should be discharged to the destination socket before devices are removed.

## ELECTRICAL CHARACTERISTICS

UNLESS OTHERWISE NOTED: VCC = +3.3V + -5% or +5.0V + -5%; TA = TMIN TO TMAX. TYPICAL VALUES ARE AT VCC = 3.3V, TA =  $+25^{\circ}$ C.

SYMBOL	PARAMETERS	Min.	TYP.	Max.	UNITS	CONDITIONS
DC CHARAC	TERISTICS					
I <sub>CC</sub>	Supply Current (RS-232)		2	30	mA	No Load, MODE = 001.
I <sub>CC</sub>	Supply Current (RS-485)		6.5	20	mA	No Load, MODE = 101.
I <sub>CC</sub>	Vcc Shutdown Current		1	20	μΑ	MODE = 111.
TRANSMITT	ER and LOGIC INPUT PINS: Pins 1, 2	, 23, 24,	25, 26, 2	7, 28		
V <sub>IH</sub>	Logic Input Voltage HIGH	2.0			V	Vcc = 3.3V.
V <sub>IH</sub>	Logic Input Voltage HIGH	2.4			V	Vcc = 5.0V.
V <sub>IL</sub>	Logic Input Voltage LOW			0.8	V	
۱ <sub>IL</sub>	Logic Input Pull-up Current			+/-15	μA	
V <sub>HYS</sub>	Logic Input Hysteresis		0.5		V	
RS-232 and	RS-485/422 RECEIVER OUTPUTS: Pin	ns 19, 20	, 21, 22			
V <sub>OH</sub>	Receiver Output Voltage HIGH	Vcc- 0.6			V	I <sub>OUT</sub> = -1.5mA.
V <sub>OL</sub>	Receiver Output Voltage LOW			0.4	V	I <sub>OUT</sub> = 2.5mA.
I <sub>OSS</sub>	Receiver Output Short-Circuit Current		+/-20	+/-60	mA	0 < Vo < Vcc.

## 3.3V - 5V PROGRAMMABLE RS-232/RS-485/RS-422 SERIAL TRANSCEIVER



UNLESS OTHERWISE NOTED: VCC = +3.3V + -5% or +5.0V + -5%; TA = TMIN to TMAX. Typical values are at VCC = 3.3V, TA =  $+25^{\circ}C$ .

SYMBOL	PARAMETERS	Min.	TYP.	Max.	UNITS	CONDITIONS
I <sub>OZ</sub>	Receiver Output Leakage Current		+/- 0.05	+/-1	μΑ	Receivers Disabled.
SINGLE-END	DED RECEIVER INPUTS (RS-232)					
	Input Voltage Range	-15		+15	V	
	Input Threshold Low	0.6	1.2		V	V <sub>CC</sub> = 3.3V.
		0.8	1.5		V	V <sub>CC</sub> = 5.0V.
	Input Threshold HIGH		1.5	2.0	V	V <sub>CC</sub> = 3.3V.
			1.8	2.4	V	V <sub>CC</sub> = 5.0V.
	Input Hysteresis		0.5		V	
	Input Resistance	3	5	7	kΩ	
DIFFERENTI	AL RECEIVER INPUTS (RS-485 / RS-4	422)		•		
R <sub>IN</sub>	Receiver Input Resistance	96			kΩ	$-7V \le V_{CM} \le +12V.$
V <sub>TH</sub>	Receiver Differential Threshold Voltage	-200	-125	-50	mV	
$\Delta V_{TH}$	Receiver Input Hysteresis		30		mV	V <sub>CM</sub> = 0V.
I <sub>IN</sub>	Input Current			125	μA	DE = 0V, V <sub>IN</sub> = 12V, Full-Duplex.
				-100	μA	DE = 0V, V <sub>IN</sub> = -7V, Full-Duplex.
SINGLE-END	DED DRIVER OUTPUTS (RS-232)					I
V <sub>O</sub>	Output Voltage Swing	+/-5.0	+/-5.4		V	Output Loaded with $3k\Omega$ to GND.
				+/-6.0	V	No Load Output.
	Short Circuit Current			+/-60	mA	V <sub>O</sub> = 0V.
	Power Off Impedance	300	10M		Ω	Vcc = 0V; V <sub>O</sub> = +/-2V.
DIFFERENTI	AL DRIVER OUTPUTS (RS-485 / RS-4	22)				I
V <sub>OD</sub>	Differential Driver Output (Tx_Out)	2		Vcc	V	$R_{L}$ = 100 $\Omega$ (RS-422), Figure 4.
		1.5		Vcc	V	$R_L = 54\Omega$ (RS-485), Figure 4.
		1.5		Vcc	V	V <sub>CM</sub> = -7V, Figure 5.
		1.5		Vcc	V	V <sub>CM</sub> = +12V, Figure 5.
$\Delta V_{OD}$	Change In Magnitude of Differential Output Voltage	-0.2		+0.2	V	$R_L$ = 54Ω or 100Ω, Figure 4.
V <sub>OC</sub>	Driver Common Mode Output Volt- age			3	V	R <sub>L</sub> = 54Ω or 100Ω, Figure 4.
$\Delta V_{OC}$	Change In Magnitude of Common Mode Output Voltage			0.2	V	R <sub>L</sub> = 54Ω or 100Ω, Figure 4.
	Driver Output Short Circuit Current			+/-250	mA	V = +12V to -7V, Figure 6.
Ι <sub>Ο</sub>	Output Leakage Current			+/-100	μΑ	DE = 0V or Shutdown, V <sub>O</sub> = +12V to -7V.



UNLESS OTHERWISE NOTED: VCC = +3.3V +/-5% or +5.0V +/-5%; TA = TMIN TO TMAX. TYPICAL VALUES ARE AT VCC = 3.3V, TA =  $+25^{\circ}$ C.

Tx_Out pins         +/-8         kV	CONDITIONS
Tx_Out pins         +/-8         kV         kV         kV $+/-3$ x         kV         x           All Other Pins $+/-2$ kV         x           TIMING CHARACTERISTICS         RS-232 (SLEW = GND, 250kbps, ONE TRANSMITTER SWITCHING)         kbps         x $t_{pHL}, t_{pL,H}$ Receiver Propagation Delay         100         ns         x $t_{pHL}, t_{pL,H}$ Receiver Skew         50         ns         x $t_{pHL}, t_{pL,H}$ Receiver Skew         100         ns         x $t_{pHL}, t_{pL,H}$ Transition-Region Slew Rate from $+3.0V$ to $-3.0V$ to $+3.0V$ 6         30         V/µs         x           RS-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING)         ms         x         x         x $t_{pHL}, t_{pL,H}$ Receiver Propagation Delay         100         ns         x         x $t_{pHL}, t_{pL,H}$ Receiver Skew         250         ns         x         x         x $t_{pHL}, t_{pL,H}$ Receiver Skew         250         ns         x         x         x $t_{pHL}, t_{pL,H}$ Transition-Region Slew Rate from $+3.0V$ 90         V/µs	
Image: constraint of the second se	IEC 61000-4-2 Air Discharge.
All Other Pins+/-2kVITIMING CHARACTERISTICSRS-232 (SLEW = GND, 250kbps, ONE TRANSMITTER SWITCHING) $Maximum Data Rate250kbpsIt_{PHL}, t_{PLH}Receiver Propagation Delay100ns0t_{PHL}, t_{PLH}Receiver Skew50ns0t_{PHL}, t_{PLH}Receiver Skew100ns0t_{PHL}, t_{PLH}Receiver Skew100ns0t_{PHL}, t_{TLH}Transition-Region Slew Rate from+3.0V to -3.0V to +3.0V630V/\mus1Maximum Data Rate1Mbps1t_{PHL}, t_{PLH}Receiver Propagation Delay100ns0t_{PHL}, t_{PLH}Receiver Skew250ns0t_{PHL}, t_{PLH}Receiver Skew250ns0t_{PHL}, t_{PLH}Transition-Region Slew Rate from+3.0V to -3.0V to +3.0V90V/\mus0t_{THL}, t_{TLH}Transition-Region Slew Rate from+3.0V to -3.0V to +3.0V250ns0t_{PHL}, t_{PLH}Driver Skew250ns1t_{DPHL}, t_{DPLH}Differential Output Propagation2501500ns1t_{DPHL}, t_{DPLH}Driver Propagation Delay Skew200ns1t_{DPLH}, t_{DPLH}Driver Propagation Delay Skew200ns1t_{DPLH}, t_{DPLH}Driver Output Enable Time200ns1t_{DPLH}, t_{DLH}D$	IEC 61000-4-2 Contact Discharge.
TIMING CHARACTERISTICSRS-232 (SLEW = GND, 250kbps, ONE TRANSMITTER SWITCHING) $Iam Maximum Data Rate250kbps1Ip_HL, Ip_LHReceiver Propagation Delay100ns0Ip_{HL}, Ip_{LH}Receiver Skew50ns0It_{PHL}, Ip_{LH} Receiver Skew100ns0It_{PHL}, Ip_{LH} Receiver Skew100ns0It_{HL}, T_{LH} Transition-Region Slew Rate from+3.0V to -3.0V to +3.0V630V/\mus1RS-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING)Maximum Data Rate1Mbps1It_{PHL}, Ip_{LH} Receiver Propagation Delay100ns0It_{PHL}, Ip_{LH} Receiver Propagation Delay100ns0It_{PHL}, Ip_{LH} Receiver Skew250ns0It_{PHL}, Ip_{LH} Driver Skew250ns0It_{PHL}, Ip_{LH} Driver Skew250ns0It_{PHL}, Ip_{LH} Driver Skew250ns0It_{PHL}, Ip_{LH} Driver Skew250ns1It_{PHL}, Ip_{LH} Driver Skew250ns1It_{PHL}, Ip_{LH} Driver Skew250ns1It_{PHL}, Ip_{LH} Driver Read Fall Time2001500ns1It_{PHL}, Ip_{LH} Driver Rise and Fall Time2001500ns1It_{DPHL}, Ip_{LH} Driver Rise and Fall Time200n$	Human Body Model.
RS-232 (SLEW = GND, 250kbps, ONE TRANSMITTER SWITCHING)Maximum Data Rate250kbpsI $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns0 $t_{PHL}, t_{PLH}$ Receiver Skew50ns0 $t_{PHL}, t_{PLH}$ Receiver Skew100ns0 $t_{PHL}, t_{PLH}$ Driver Skew100ns0 $t_{THL}, t_{TLH}$ Transition-Region Slew Rate from +3.0V to -3.0V to +3.0V630V/ $\mu$ sRS-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING)Maximum Data Rate1Mbps1 $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns0 $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns0 $t_{PHL}, t_{PLH}$ Driver Skew50ns01 $t_{PHL}, t_{PLH}$ Driver Skew250ns00 $t_{PHL}, t_{PLH}$ Driver Skew250ns00RS-485/RS-422 (SLEW = GND, 250kbps, ONE TRANSMITTER SWITCHING)Maximum Data Rate2501500ns1 $t_{DPHL}, t_{DPLH}$ Differential Output Propagation Delay Time2501500ns1 $t_{R}, t_F$ Driver Rise and Fall Time2001500ns1 $t_{DPHL}, t_{DPLH}$ Driver Output Enable Time2001s00ns1 $t_{DHL}, t_{DLH}$ Receiver Propagation Delay Skew250ns1 $t_{DHL}, t_{PLH}$ Receiver Propagation Delay150ns1 </td <td>Human Body model.</td>	Human Body model.
Maximum Data Rate250kbpskbps $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns0 $t_{PHL}, t_{PLH}$ Receiver Skew50ns0 $t_{PHL}, t_{PLH}$ Receiver Skew100ns0 $t_{PHL}, t_{PLH}$ Driver Skew100ns0 $t_{THL}, t_{TLH}$ Transition-Region Slew Rate from +3.0V to -3.0V to +3.0V630 $V/\mu s$ RS-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING)Rs-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING)Receiver Propagation Delay100ns0 $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns0 $t_{PHL}, t_{PLH}$ Receiver Skew50ns0 $t_{PHL}, t_{PLH}$ Prover Skew25ns0 $t_{THL}, t_{TLH}$ Transition-Region Slew Rate from +3.0V to -3.0V or -3.0V to +3.0V90 $V/\mu s$ 0RS-485/RS-422 (SLEW = GND, 250kbps, ONE TRANSMITTER SWITCHING)Maximum Data Rate2501500ns1 $t_{DPHL}, t_{DPLH}$ Differential Output Propagation Delay Time2501500ns1 $t_{DPHL}, t_{DPLH}^{-}$ Driver Rise and Fall Time2001500ns1 $t_{DHZ}, t_{DZL}$ Driver Output Enable Time900ns1 $t_{DHL}, t_{DLH}^{-}$ Receiver Propagation Delay150ns1 $t_{DHL}, t_{DLH}^{-}$ Receiver Propagation Delay150ns1 $t_{DHL}, t_{DLH}^{-}$ Driver Output En	
$t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns1 $ t_{PHL}-t_{PLH} $ Receiver Skew50ns1 $ t_{PHL}-t_{PLH} $ Driver Skew100ns1 $t_{THL}, t_{TLH}$ Transition-Region Slew Rate from +3.0V to -3.0V to +3.0V630 $V/\mu s$ 1RS-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING)RS-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING) $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns1 $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns1 $t_{PHL}, t_{PLH} $ Receiver Skew50ns1 $t_{PHL}, t_{PLH} $ Driver Skew25ns1 $t_{PHL}, t_{PLH} $ Driver Skew25ns1 $t_{THL}, t_{TLH} $ Transition-Region Slew Rate from +3.0V to -3.0V to +3.0V90 $V/\mu s$ 1 $t_{PHL}, t_{PLH} $ Driver Skew2501500ns1 $t_{DPHL}, t_{DPLH} $ Differential Output Propagation Delay Time2501500ns1 $t_{DPHL}, t_{DPLH} $ Driver Rise and Fall Time2001500ns1 $t_{DPLH}, t_{DLH} $ Driver Output Enable Time900ns1 $t_{DHZ}, t_{DLZ} $ Driver Output Disable Time900ns1 $t_{DHL}, t_{PLH} $ Receiver Enable to Output High50ns1	
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$R_{L} = 3k\Omega, C_{L} = 1000pF.$
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	C <sub>L</sub> = 150pF.
trilltrueTransition-Region Slew Rate from +3.0V to -3.0V or -3.0V to +3.0V630 $V/\mu s$ 1RS-232 (SLEW = Vcc, 1Mbps, ONE TRANSMITTER SWITCHING)Maximum Data Rate1Mbps1 $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns0 $t_{PHL}, t_{PLH}$ Receiver Skew50ns0 $t_{PHL}, t_{PLH}$ Receiver Skew25ns0 $t_{PHL}, t_{TLH}$ Transition-Region Slew Rate from +3.0V to -3.0V to +3.0V90 $V/\mu s$ 0 $t_{THL}, t_{TLH}$ Transition-Region Slew Rate from +3.0V to -3.0V to +3.0V90 $V/\mu s$ 0 $t_{THL}, t_{TLH}$ Transition-Region Slew Rate from +3.0V to -3.0V to +3.0V90 $V/\mu s$ 0 $t_{DHL}, t_{DLH}$ Driver GND, 250kbps, ONE TRANSMITTER SWITCHING)01Maximum Data Rate2501500ns1 $t_{DPHL}, t_{DPLH}$ Differential Output Propagation Delay Time2501500ns1 $t_{DLH}, t_{DLH}$ Driver Rise and Fall Time2001500ns1 $t_{DHL}, t_{DLH}$ Driver Output Enable Time900ns1 $t_{DHL}, t_{DLH}$ Driver Output Enable Time900ns1 $t_{DHL}, t_{DLH}$ Receiver Propagation Delay50ns1 $t_{DHL}, t_{DLH}$ Receiver Propagation Delay150ns1 $t_{DHL}, t_{DLH}$ Receiver Propagation Delay150ns1 $t_{DHL}, t_{DLH}$ Receiver Enable	C <sub>L</sub> = 150pF.
H.H. H.H. $+3.0V$ to $-3.0V$ or $-3.0V$ to $+3.0V$ Image: Second se	
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$t_{PHL}, t_{PLH}$ Receiver Propagation Delay100ns<	
InternalAnd And And And And And And And And And	$R_L = 3k\Omega$ , $C_L = 250pF$ .
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Hand Har+3.0V to -3.0V or -3.0V to +3.0VImage: Section of the	
Maximum Data Rate250kbpsI $t_{DPHL}, t_{DPLH}$ Differential Output Propagation Delay Time2501500nsI $t_{R}, t_{F}$ Driver Rise and Fall Time2001500nsI $ t_{DPHL}^-, t_{DPLH} $ Driver Propagation Delay Skew2001500nsI $t_{DZH}, t_{DZL}$ Driver Output Enable Time200900nsI $t_{DHZ}, t_{DLZ}$ Driver Output Disable Time2001500nsI $t_{PHL}, t_{PLH}$ Receiver Propagation Delay100150nsI $t_{ZH}$ Receiver Enable to Output High5010nsI	Vcc = 3.3V, $R_L$ = 3k $\Omega$ to 7k $\Omega$ , C <sub>L</sub> = 150pF to 1000pF.
$t_{DPHL}, t_{DPLH}$ Differential Output Propagation Delay Time2501500ns1 $t_{R}, t_{F}$ Driver Rise and Fall Time2001500ns1 $ t_{DPHL}^{-}, t_{DPLH} $ Driver Propagation Delay Skew2001500ns1 $t_{DHL}, t_{DZL}$ Driver Output Enable Time200900ns1 $t_{DHZ}, t_{DLZ}$ Driver Output Disable Time900ns1 $t_{PHL}, t_{PLH}$ Receiver Propagation Delay150ns1 $t_{ZH}$ Receiver Enable to Output High50ns1	
Delay TimeImage: Constraint of the second seco	$R_{DIFF}$ = 54 $\Omega$ , $C_{L}$ = 50pF.
$ t_{DPHL}^{-} _{t_{DPLH} }$ Driver Propagation Delay Skew200nsI $t_{DPLH} $ Driver Output Enable Time900nsI $t_{DZH}, t_{DZL}$ Driver Output Enable Time900nsI $t_{DHZ}, t_{DLZ}$ Driver Output Disable Time900nsI $t_{PHL}, t_{PLH}$ Receiver Propagation Delay150nsI $t_{ZH}$ Receiver Enable to Output High50nsI	Figures 7 and 8.
$t_{DPLH}$ Driver Output Enable Time900nsI $t_{DZH}, t_{DZL}$ Driver Output Enable Time900nsI $t_{DHZ}, t_{DLZ}$ Driver Output Disable Time900nsI $t_{PHL}, t_{PLH}$ Receiver Propagation Delay150nsI $t_{ZH}$ Receiver Enable to Output High50nsI	Figures 7 and 8.
totalDriver Output Disable Time900nsIt_{PHL}, t_{PLH}Receiver Propagation Delay150nsIt_{ZH}Receiver Enable to Output High50nsI	Figures 7 and 8.
t <sub>PHL</sub> , t <sub>PLH</sub> Receiver Propagation Delay     150     ns     I       t <sub>ZH</sub> Receiver Enable to Output High     50     ns     I	Figures 9, 10, 11 and 12.
t <sub>ZH</sub> Receiver Enable to Output High 50 ns I	Figures 9, 10, 11 and 12.
	Figures 13 and 14.
	Figures 15 and 16.
	Figures 15 and 17.
t <sub>HZ</sub> Receiver Output High to Disable 50 ns I	Figures 15 and 18.

## Exar Dewering Connectivity REV. 1.0.0

## 3.3V - 5V PROGRAMMABLE RS-232/RS-485/RS-422 SERIAL TRANSCEIVER

NEV. 1.0.0

UNLESS OTHERWISE NOTED: VCC = +3.3V + -5% or +5.0V + -5%; TA = TMIN to TMAX. Typical values are at VCC = 3.3V, TA =  $+25^{\circ}C$ .

SYMBOL	PARAMETERS	Min.	TYP.	Max.	UNITS	CONDITIONS			
t <sub>LZ</sub>	Receiver Output Low to Disable		50		ns	Figures 15 and 19.			
RS-485/RS-42	RS-485/RS-422 (SLEW = Vcc, 10Mbps, ONE TRANSMITTER SWITCHING)								
	Maximum Data Rate			10	Mbps	$R_{DIFF}$ = 54 $\Omega$ , $C_{L}$ = 50pF.			
t <sub>DPHL</sub> , t <sub>DPLH</sub>	Differential Output Propagation Delay Time		60	120	ns	Figures 7 and 8.			
t <sub>R,</sub> t <sub>F</sub>	Driver Rise and Fall Time		10	25	ns	Figures 7 and 8.			
│t <sub>DPHL</sub> - t <sub>DPLH</sub> │	Driver Propagation Delay Skew			10	ns	Figures 7 and 8.			
t <sub>DZH</sub> , t <sub>DZL</sub>	Driver Output Enable Time			900	ns	Figures 9, 10, 11 and 12.			
t <sub>DHZ</sub> , t <sub>DLZ</sub>	Driver Output Disable Time			900	ns	Figures 9, 10, 11 and 12.			
t <sub>PHL</sub> , t <sub>PLH</sub>	Receiver Propagation Delay			150	ns	Figures 13 and 14.			
t <sub>ZH</sub>	Receiver Enable to Output High		32		ns	Figures 15 and 16.			
t <sub>ZL</sub>	Receiver Enable to Output Low		32		ns	Figures 15 and 17.			
t <sub>HZ</sub>	Receiver Output High to Disable		40		ns	Figures 15 and 18.			
t <sub>LZ</sub>	Receiver Output Low to Disable		40		ns	Figures 15 and 19.			



### **1.0 FUNCTION TABLES**

The SP336E drivers and receivers may be configured to operate as either standard RS-485/RS-422 or RS-232 devices. RS-485/RS422 drivers have differential outputs and receivers have differential inputs. RS-232 drivers and receivers are single-ended with inverting outputs.

Drivers			Receivers		
Inputs		Outputs		Inputs	Output
Tx_EN	Tx_In	Tx(A)	Tx(B)	Rx(A) - Rx(B)	RxOut
1	1	0	1	> -50mV	1
1	0	1	0	≤ <b>-</b> 200mV	0
0	х	High-Z		Open / Shorted	1

TABLE 1: R-485/RS-422 FULL DUPLEX: MODE 011 (T3, R3), MODE 101 (T1, T3, R1, R3)

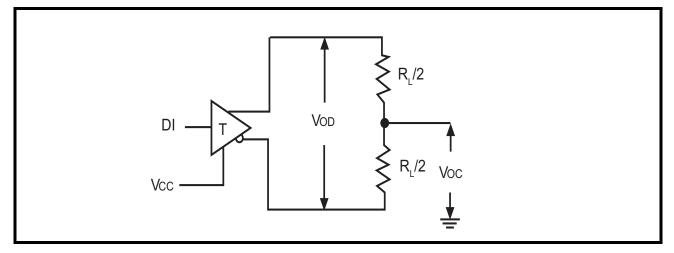
R3)

TRANSMITTING			RECEIVING			
Inputs		Outputs		Inputs		Outputs
DE/RE	TxIn	Tx(A)	Tx(B)	DE/RE	Rx(A) - Rx(B)	RxOut
1	1	0	1	1	x	High-Z
1	0	1	0	1	x	High-Z
				0	> -50mV	1
0 x	High-Z	High-Z	0	≤ -200mV	0	
				0	Open / Shorted	1

Driv	/ERS	Rece	IVERS
Input	Output	Input	Output
0	$\geq$ 5V	$\ge 3V$	0
1	≤ <b>-</b> 5V	≤ <b>-</b> 3V	1
Open	≤ <b>-</b> 5V	Open	1



## FIGURE 4. RS-485 DRIVER DC TEST CIRCUIT



### FIGURE 5. RS-485 DRIVER COMMON MODE LOAD TEST

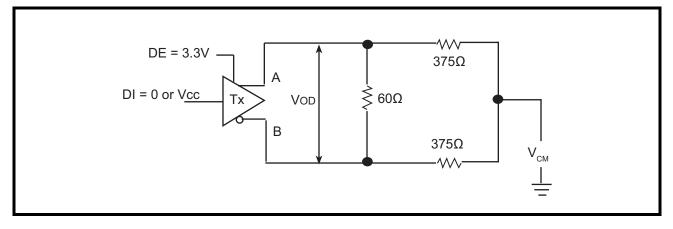
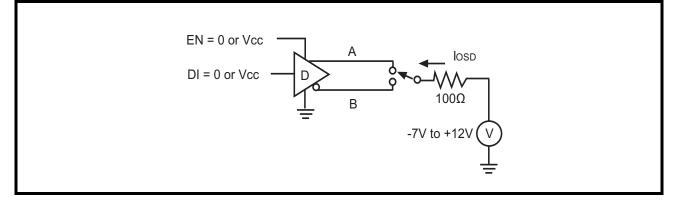
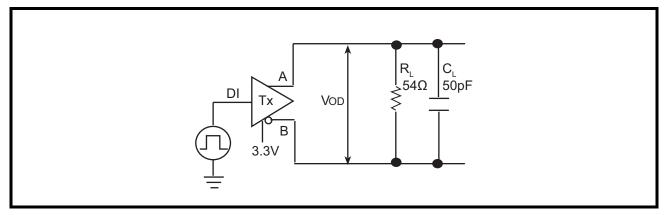


FIGURE 6. RS-485 DRIVER OUTPUT SHORT CIRCUIT TEST





#### FIGURE 7. RS-485 DRIVER PROPAGATION DELAY TEST CIRCUIT



#### FIGURE 8. RS-485 DRIVER TIMING DIAGRAM

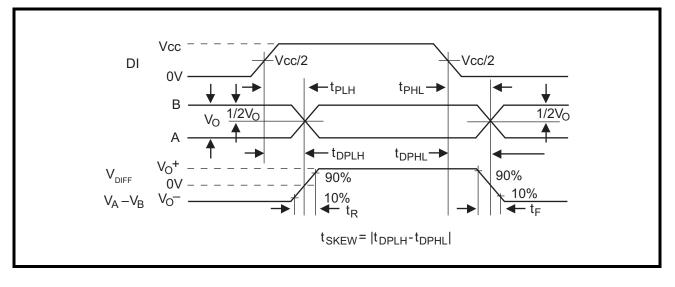
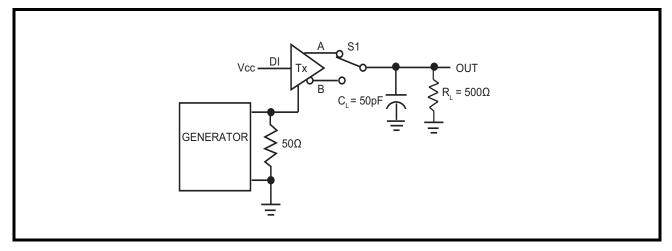


FIGURE 9. RS-485 DRIVER ENABLE AND DISABLE TEST CIRCUIT







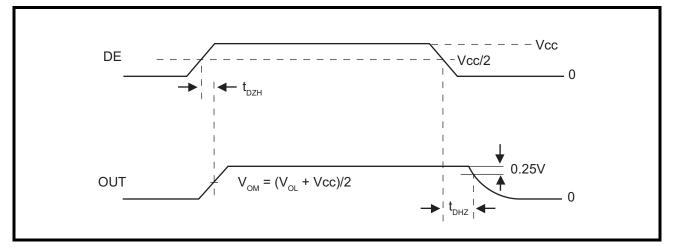
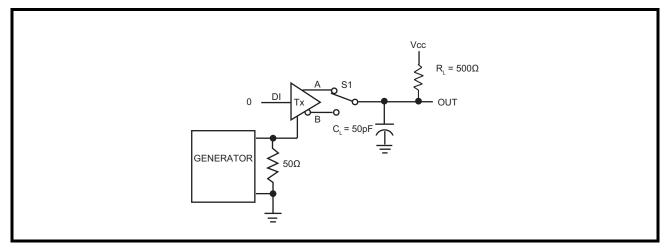
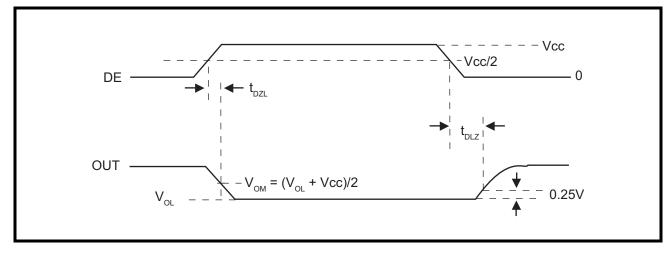


FIGURE 11. RS-485 DRIVER ENABLE AND DISABLE TEST CIRCUIT 2

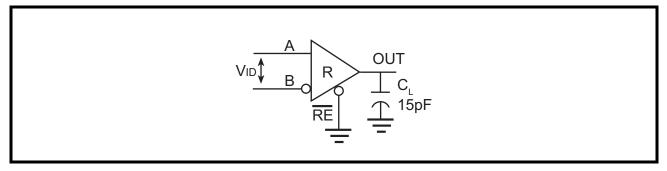














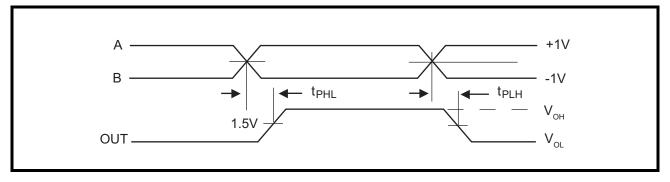
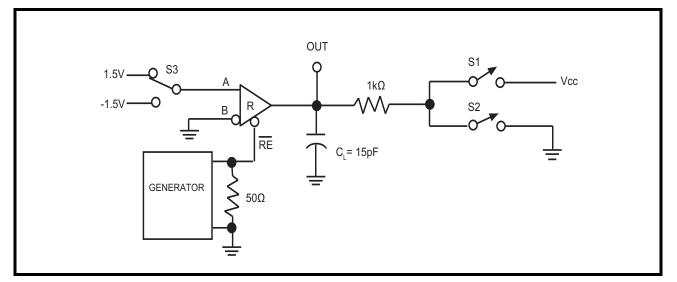
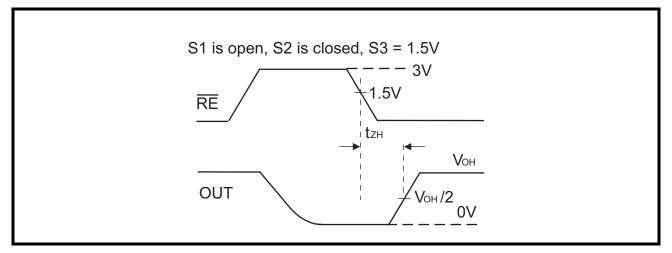


FIGURE 15. RS-485 RECEIVER ENABLE AND DISABLE TIMES TEST CIRCUIT

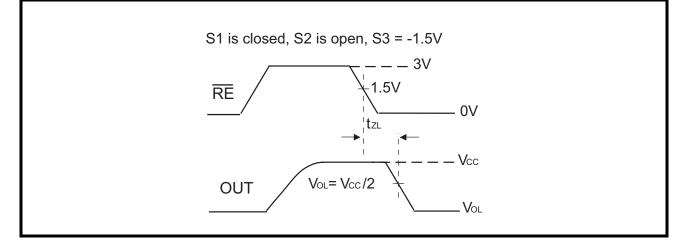






### FIGURE 16. RS-485 RECEIVER ENABLE AND DISABLE TIMES TIMING DIAGRAM 1









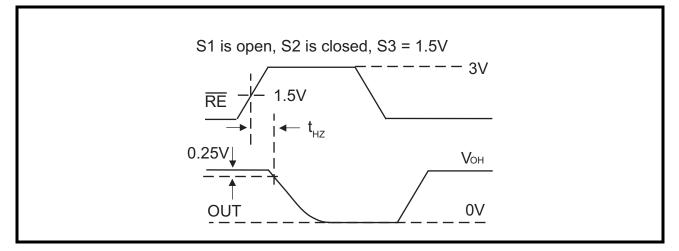


FIGURE 19. RS-485 RECEIVER ENABLE AND DISABLE TIMES TIMING DIAGRAM 4

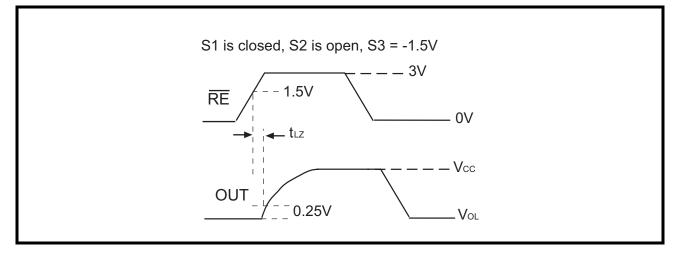
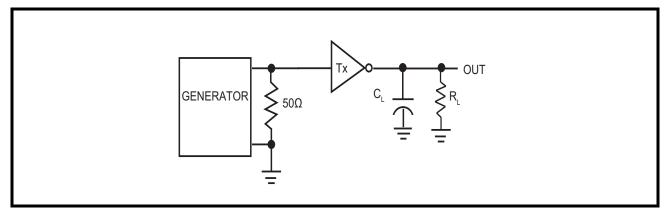
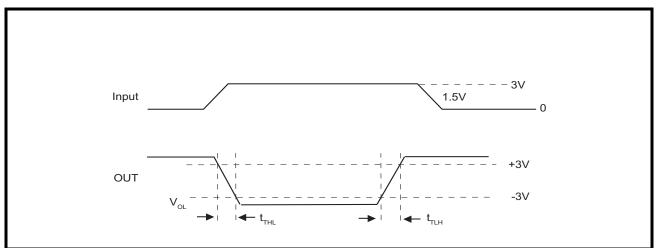


FIGURE 20. RS-232 DRIVER OUTPUT SLEW RATE TEST CIRCUIT

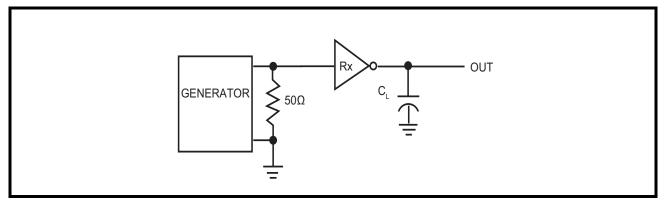




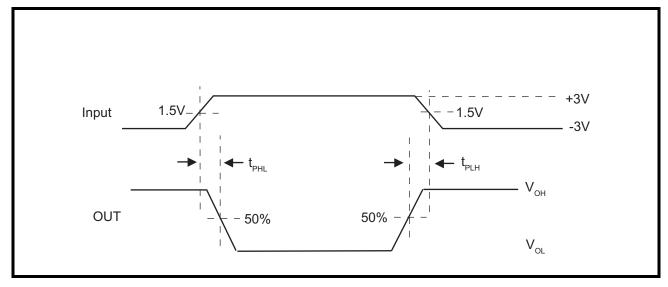














### 2.0 SUGGESTED APPLICATION DIAGRAMS

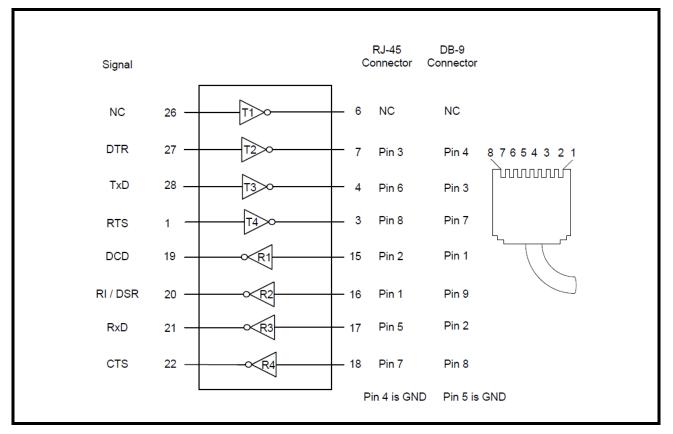
The SP336E supports all signals used in RS-232 over an 8 pin modular jack (RJ-45) as defined in TIA/EIA-561. For DTE serial port only three drivers are required. Driver\_1 is not used in this configuration and its driver input should be tied to high or low.

SP336E may also be used to implement a standard serial port over a DB-9 connector (TIA/EIA-574 or the standard IBM serial port). In that case either DSR or RI signal can be supported. Both DSR and RI are used mainly for dial-up connections and are typically not needed on dedicated lines. If both signals are required, add a discrete transceiver such as SP3220E.

An alternative implementation would be to use the SP336E to emulate the functionality of two dual-channel RS-232 transceivers (2 x SP232's or equivalent).

### Loop-Back

Changing from RS-232 mode (MODE 001) to loop-back mode (MODE 000) duplicates the function of an external loop-back plug. Loop-back can be used to test serial port functionality or to diagnose faults.



### FIGURE 24. RS-232E SERIAL PORT (EIA-561 / EIA-574)

### 3.3V - 5V PROGRAMMABLE RS-232/RS-485/RS-422 SERIAL TRANSCEIVER



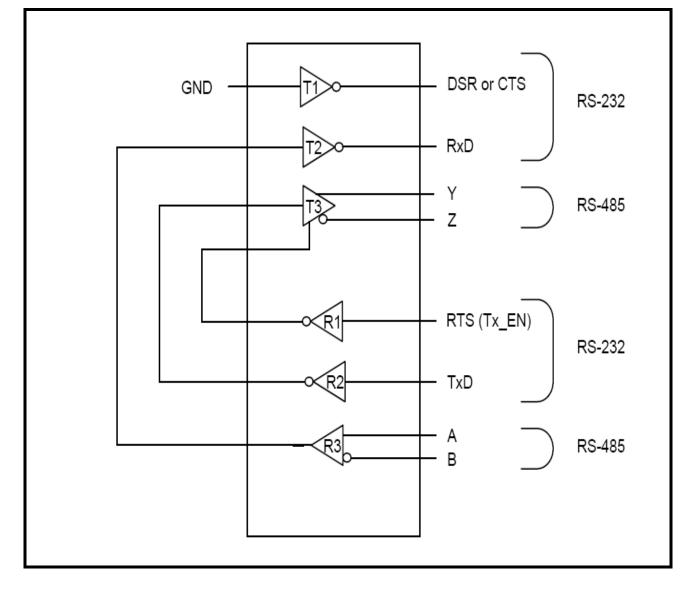
#### RS-232 to RS-485 Translator

SP336E can be used to implement a single-chip RS-232 to RS-485 translator function. Both full-duplex (4-wire RS-485) and half-duplex (2-wire RS-485) configurations are shown. RS-485 is capable of communicating on data cables up to 4000 feet (1200 meter) which makes it an ideal interface for extending the reach of short-range serial ports like RS-232. The configurations shown can be used to connect directly to existing PC type RS-232 serial ports to enable extended-reach communication.

The RTS signal (circuit CA or 105) is used as a transmit direction control signal for half-duplex. The ON condition puts the repeater into transmit mode and inhibits receive. On a half-duplex channel RxD should be held in MARK state (binary 1) when receiver 3 is inactive. Driver 1 on the SP336E can be used to generate DSR or CTS signal to indicate to the host terminal that the translator is powered-on and ready.

#### Shutdown Modes

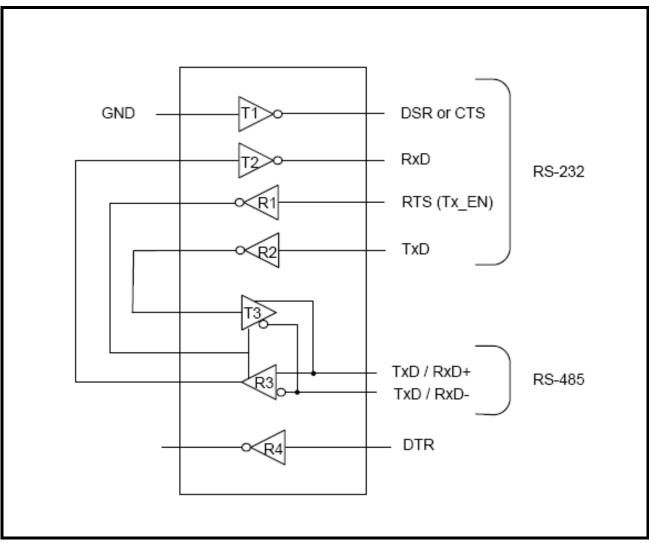
SP336E features two shutdown modes. In mode 111 (full shutdown) all drivers and receivers are at high impedance. In mode 110, all drivers are tri-state but all four receivers remain active. In modes 101 and 100 two differential receivers can be kept active while the differential drivers are tri-stated using the Tx\_EN inputs.



#### FIGURE 25. RS-232 / RS-485 TRANSLATOR FULL-DUPLEX CABLE-EXTENDER (MODE 011)







### 3.3V - 5V PROGRAMMABLE RS-232/RS-485/RS-422 SERIAL TRANSCEIVER



#### **Bus Repeater**

Mode 101 can be used as a bus-repeater to extend the reach of an RS-422 bus. This configuration is best suited for point-to-point or multi-drop communications because the drivers are always active and echoing data from their corresponding receiver.

For applications where multiple nodes are allowed to transmit, some type of bus arbitration should be used. One technique would be to use SP336E in conjunction with external decoder logic, packet buffers and node address fields embedded in the data stream. Receiving the correct node address triggers Tx\_EN to pass data onward.

Mode 100 could implement a repeater / gateway to partition or extend RS-485 networks. Direction Control determines when data is forwarded to or from segments A and B.

#### FIGURE 27. RS-422 BUS-REPEATER (MODE 101)

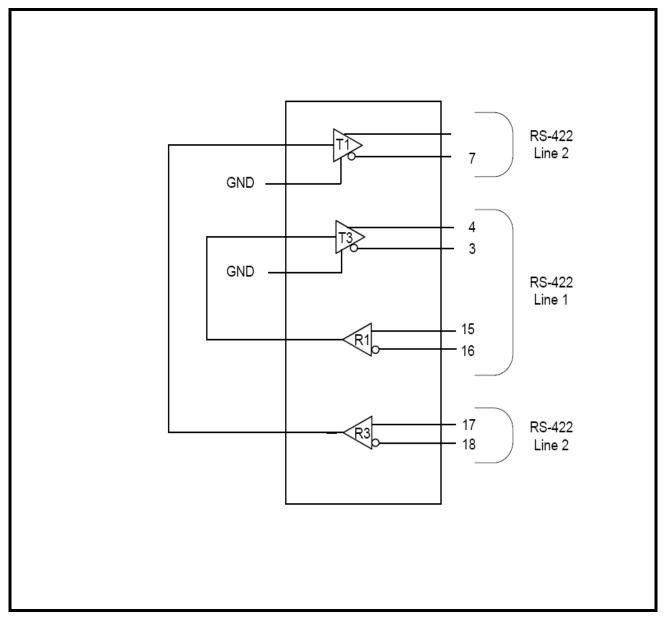
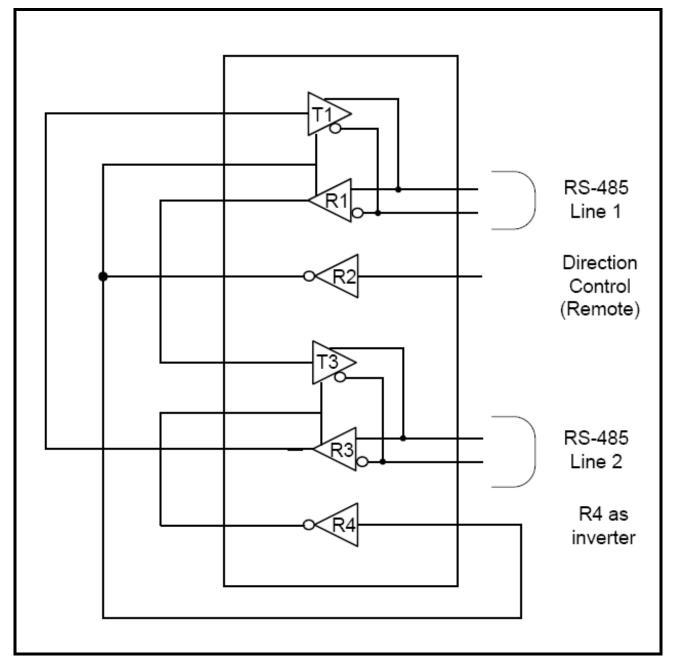


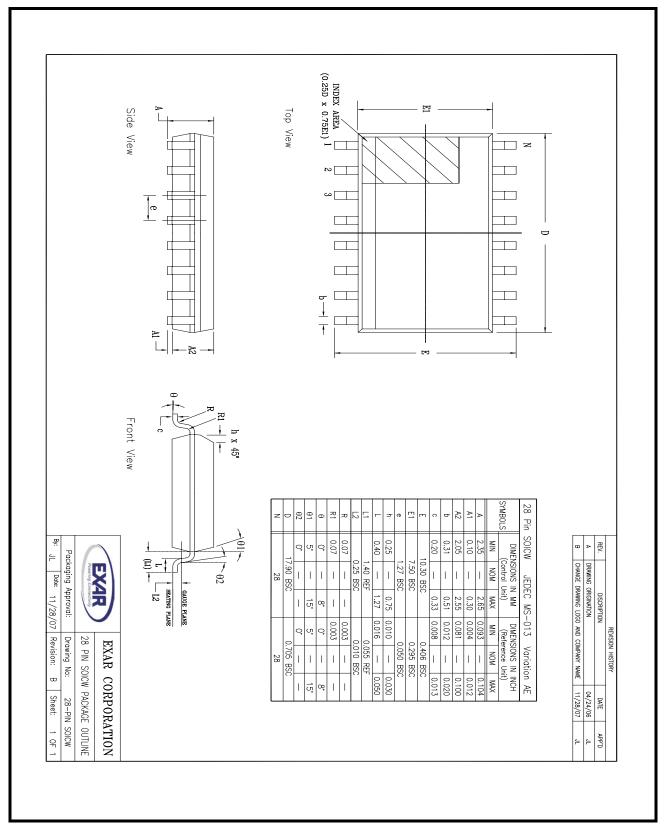


FIGURE 28. RS-485 BUS-REPEATER (MODE 100)



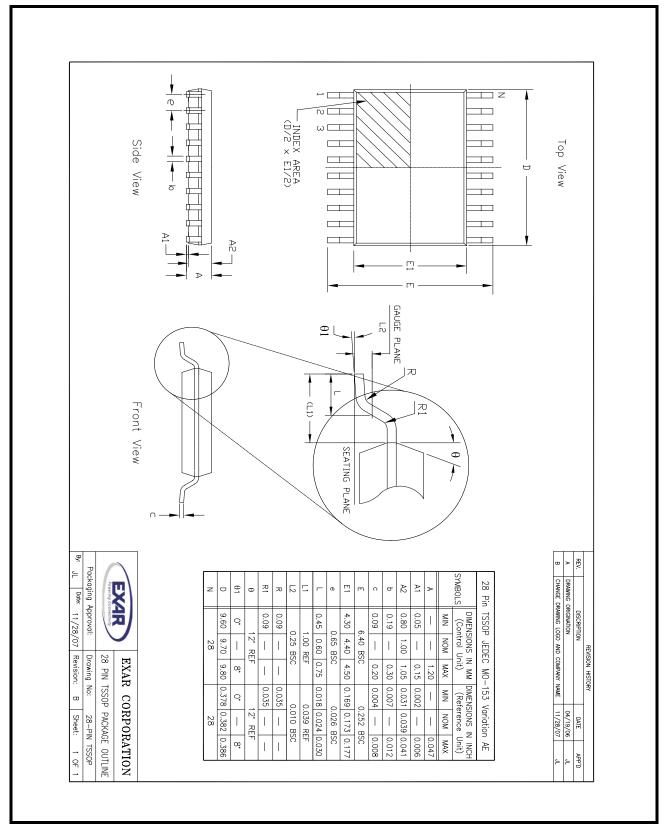


#### FIGURE 29. 28 PIN SOICW PACKAGE OUTLINE DRAWING











### **REVISION HISTORY**

DATE	REVISION	DESCRIPTION
March 2010	1.0.0	Production Release.

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