## General Description

The AAT1451 is a highly integrated, high efficiency LED backlight solution for notebook, netbook computers, monitors and portable TVs. The device operates from DC inputs, cigarette adapters or multi-cell Li-ion batteries in the voltage range from 5 V to 26 V .

An integrated boost (step-up) converter provides a high voltage output up to 50 V for driving series LEDs. Four precision current sinks are programmable up to 30 mA per string through one external $\mathrm{R}_{\text {SET }}$ resistor, supporting up to $48^{1}$ white LEDs at 120 mA total output current.
The boost output voltage is determined by the highest total forward voltage of the LED strings, allowing for a wide range of LED characteristics. Each string is PWM dimmed with 90 degree phase shift to minimize ripple currents, and filter capacitor sizes. The PWM input frequency range is 100 Hz to 10 kHz with a dimming range of 256:1.

The integrated boost regulator switching frequency is programmable from 600 kHz to 1 MHz by external resistor for optimum efficiency and the smallest external L/C filtering components.
Boost current mode control provides fast response to line and load transients. Integrated light-load mode ensures highest efficiency across the entire load range.
Fault tolerant circuitry extends system life by disabling open and shorted LED(s) strings. The unique high voltage current sinks prevent damage resulting from shorted LEDs. The FAULT pin indicates the presence of shorted LEDs or over-temperature conditions.

The AAT1451 is available in a Pb-free, thermally enhanced 16-pin $3 \times 4$ TDFN package.

## Features

- $\mathrm{V}_{\mathrm{IN}}$ Range: 5 V to 26 V
- Integrated 50 V Boost Converter
- Maximum Iout: 120 mA
- Programmable Switching Frequency
- 600 kHz to 1 MHz
- Up to 93\% Efficiency
- High Efficiency Light-Load Mode
- Four White LED Strings
- Programmable Max Current Sink up to 30 mA Each
- $\pm 2 \%$ Accuracy ( 22 mA )
- $\pm 1.5 \%$ Matching ( 22 mA )
- Direct PWM Dimming
- Automatic Phase Shifting
- Fast Turn-On/Off
- Integrated Fault Protection for
- Independent Disable of Open/Shorted LED(s) String(s)
- Over-Voltage
- Over-Temperature
- FAULT Indication for Shorted LED(s) and OverTemperature
- Soft-Start Minimizes Inrush Current
- TDFN34-16 Low Profile Package
- $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ Temperature Range


## Applications

- Monitors
- Notebook and Netbook Computers
- Portable DVD Players
- Portable TV
- White LED Backlight

[^0]
## Typical Application Circuit



## Pin Descriptions

| Pin \# | Symbol | Function | Description |
| :---: | :---: | :---: | :--- |
| 1 | PGND | GND | Power Ground. Connect to GND underneath the IC. |
| 2 | VIN | I | Input voltage to IC. Tied to input voltage source and input boost inductor. |
| 3 | FSLCT | I | Connect an external resistor to set boost switching frequency from 600kHz to 1MHz. |
| 4 | ISET | I | Connect resistor to ground to set maximum current up to 30mA through the LED strings. |
| 5 | FB1 | O | Output current sink 1. Connect to GND to disable channel 1. |
| 6 | FB2 | O | Output current sink 2. Connect to GND to disable channel 2. |
| 7 | FB3 | O | Output current sink 3. Connect to GND to disable channel 3. |
| 8 | FB4 | O | Output current sink 4. Connect to GND to disable channel 4. |
| 9 | FAULT | O | Open drain FAULT signal. Pull up to VDD with external resistor. Low indicates a shorted LED <br> condition. |
| 10 | VDD | I/O | Internal regulated voltage when operating from input voltage range 5.0V to 26.0V. De-couple <br> with a 2.2pF capacitor to ground. Do not source current from this node. |
| 11 | PWM | I | PWM input pin. Connect logic level PWM input signal in the frequency range 100Hz-10kHz to <br> this pin to enable PWM dimming. |
| 12 | SHDN | I | Logic high to enable the device. Logic low disables the device and minimizes quiescent current <br> and also disables the internal linear regulator. |
| 13 | COMP | I | Connect an external resistor in series with a capacitor to ground to compensate the boost <br> converter. |
| 14 | AGND | AGND | Connect to AGND |
| 15 | OVP | I | Over-voltage protection pin. Connect to output of boost converter through a resistor divider. <br> 16 |
| SW | O | Switching node of boost converter. Connect an inductor between this pin and input voltage <br> source. Connect the Schottky diode between this pin and boost output capacitor. |  |
| EP |  | PGND | Exposed paddle. Connect to PCB PGND plane. Input and output capacitor GND should connect <br> to EP. |

## Pin Configuration

TDFN34-16
(Top View)


## Absolute Maximum Ratings ${ }^{1}$

| Symbol | Description | Value | Units |
| :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {sw }}$ | Voltage to GND | 50 | V |
| $\mathrm{V}_{\text {IN }}$ | Input Voltage to GND | -0.3 to 30 |  |
| $\mathrm{V}_{\text {FBX }}$ | Output Current Sinks FB1 - FB4 to GND | -0.3 to 40 |  |
| $\mathrm{V}_{\text {DD }} \mathrm{V}_{\text {FAULT }}$ | Low Voltage Pin to GND | -0.3 to 7.0 |  |
| $\overline{\text { SHDN, }}$, COMP, PWM, ISET, FSLCT, OVP | Voltage to GND | -0.3 to $V_{D D}+0.3$ |  |
| $\mathrm{I}_{\text {Out }}$ | Maximum DC Output Current ${ }^{2}$ | 134 | mA |
| TJ | Maximum Junction Operating Temperature | -40 to +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {LEAD }}$ | Maximum Soldering Temperature (at leads, 10 sec .) | 300 |  |
| $\mathrm{P}_{\mathrm{D}}$ | Maximum Power Dissipation ${ }^{3}$ | 2 | W |
| $\Theta_{\text {JA }}$ | Thermal Resistance ${ }^{3,4}$ | 50 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

## Recommended Operating Conditions

| Symbol | Description | Value | Units |
| :---: | :--- | :---: | :---: |
| $\mathrm{V}_{\text {IN }}$ | Input VoItage Range | 5 to 26 | V |
| $\mathrm{~V}_{\text {OUT }}$ | Output Voltage Range | $\mathrm{V}_{\text {IN }}+3$ to 45 |  |
| $\mathrm{~F}_{\text {PWM }}$ | PWM Dimming Frequency Range | 0.1 to 10 | kHz |
| $\mathrm{T}_{\mathrm{A}}$ | Operating Ambient Temperature | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{J}}$ | Operating Junction Temperature | -40 to 130 |  |

[^1]
## Electrical Characteristics ${ }^{1}$

$\mathrm{V}_{\text {IN }}=12 \mathrm{~V} ; \mathrm{C}_{\text {IN }}=2.2 \mu \mathrm{~F}, \mathrm{C}_{\text {out }}=2.2 \mu \mathrm{~F} ; \mathrm{C}_{\mathrm{VDD}}=2.2 \mu \mathrm{~F} ; \mathrm{L}_{1}=4.7 \mu \mathrm{H} ; \mathrm{R}_{\text {SET }}=7.5 \mathrm{k} \Omega\left(\mathrm{I}_{\text {FBx }}=22 \mathrm{~mA}\right) ; \mathrm{R}_{\text {FSGIT }}=20 \mathrm{k} \Omega ; \mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$.

| Symbol | Description | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supply, Current Sinks |  |  |  |  |  |  |
| $\mathrm{V}_{\text {IN }}$ | Input Voltage Range |  | 5.0 |  | 26.0 | V |
| Vuvio | Under-Voltage Threshold | $\mathrm{V}_{\text {IV }}$ Rising |  |  | 4.3 | V |
|  |  | Hysteresis |  | 500 |  | mV |
|  |  | $\mathrm{V}_{\text {IN }}$ Falling | 3.2 |  |  | V |
| $V_{D D}$ | VDD Output Voltage | $\overline{\text { SHDN }}=$ Logic High, $\mathrm{I}_{\mathrm{DD}(\text { Out }}=0 \mathrm{~mA}$ | 4.0 | 4.5 | 6.0 | v |
| $\mathrm{V}_{\text {fbx }}$ | Current Sink Voltage | $\begin{aligned} & \mathrm{SHDN}=\text { Logic High, } \mathrm{I}_{\mathrm{FBx}}=22 \mathrm{~mA} \\ & \left(\mathrm{R}_{\text {SET }}=7.5 \mathrm{k} \Omega\right) \end{aligned}$ |  | 0.3 |  | V |
| $\mathrm{V}_{\text {Fbx(SHORT) }}$ | Shorted Diode(s) Detection Threshold | $\mathrm{I}_{\mathrm{Fbx}}=30 \mathrm{~mA}$ |  | 5 |  | V |
| $\mathrm{I}_{2}$ | IN Quiescent Current | FB1-FB4 = Open, SHDN= Logic low |  | 3 |  | mA |
| $\mathrm{I}_{\text {SD }}$ | IN Pin Shutdown Current | FB1-FB4 $=$ Open, $\overline{\text { SHDN }}=\mathrm{V}_{\text {PwM }}=$ Logic low, does not include SW leakage current |  |  | 40.0 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {Ebx }}$ | Current Sink Accuracy | $\mathrm{I}_{\mathrm{Ebx}}=22 \mathrm{~mA}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ | -5 | $\pm 2$ | +5 | \% |
| $\mathrm{I}_{\text {fex-Matching }}$ | Current Matching Between Any Sink Channel | $\mathrm{I}_{\mathrm{Fbx}}=22 \mathrm{~mA}$ | -2 | $\pm 1.5$ | +2 | \% |
| $V_{\text {ovp }}$ | Over Voltage Threshold | $\mathrm{V}_{\text {out }}$ Rising | 1.1 | 1.2 | 1.3 | V |
|  | Over Voltage Hysteresis | $V_{\text {out }}$ Falling |  | 100 |  | mV |
| $\mathrm{R}_{\text {DSSonLo }}$ | Low Side Switch ON Resistance | $\mathrm{V}_{\mathrm{DD}}=4.5 \mathrm{~V}$ |  | 500 |  | ms |
| $\mathrm{D}_{\text {max }}$ | Maximum Duty Cycle |  | 90 |  |  | \% |
| $\mathrm{T}_{\text {min }}$ | Minimum On-Time |  |  | 100 |  | ns |
| $\mathrm{V}_{\text {ISET }}$ | Voltage at ISET |  |  | 0.6 |  | v |
| $\mathrm{V}_{\text {fScit }}$ | Voltage at FSCLT |  |  | 0.6 |  | V |
| $\mathrm{I}_{\text {FBx }} / \mathrm{I}_{\text {RSET }}$ | Current Set Ratio | $\mathrm{I}_{\text {EBK }} / \mathrm{I}_{\text {ISET }}, \mathrm{V}_{\text {ISET }}=0.6 \mathrm{~V}$ |  | 264 |  | A/A |
| I | Low Side Switch Current Limit | $\mathrm{V}_{\text {IN }}=5.0 \mathrm{~V}$ to 26.0 V | 3.0 |  | 5.0 | A |
| $\mathrm{I}_{\text {LeAK }}$ | SW Pin Leakage | SHDN $=$ Logic Low, $\mathrm{V}_{\text {Sw }}=45 \mathrm{~V}$ |  |  | 1 | $\mu \mathrm{A}$ |
|  | FBx Pin Leakage | $\mathrm{V}_{\text {Fbx }}=30 \mathrm{~V}, \mathrm{~V}_{\text {PWM }}=$ logic high |  |  | 10 | $\mu \mathrm{A}$ |
| Fosc | Oscillator Frequency | $\mathrm{R}_{\mathrm{fS}}=20 \mathrm{k} \Omega$ | 850 | 1000 | 1150 | kHz |
| $\mathrm{F}_{\text {pumi(max) }}$ | Maximum Input PWM Frequency ${ }^{1}$ |  | 100 |  | 10000 | Hz |
| $\mathrm{F}_{\text {Pumoomax) }}$ | Maximum Output PWM Frequency |  | 6750 | 8000 | 9250 | Hz |
| Tss | Soft-Start Time | $\mathrm{V}_{\text {out }}=35 \mathrm{~V}, \mathrm{C}_{\text {comp }}=18 \mathrm{nF}, \mathrm{R}_{\text {comp }}=10 \mathrm{k} \Omega$ |  | 1.5 |  | ms |
| Logic Level Inputs: SHDN, PWM |  |  |  |  |  |  |
| $\mathrm{V}_{\text {LSHON }}$ | SHDN Threshold Low |  |  |  | 0.4 | V |
| $\mathrm{V}_{\mathrm{L}}$ | PWM Threshold Low |  |  |  | 0.8 | V |
| $\mathrm{V}_{\mathrm{H}}$ | PWM and SHDN Threshold High |  | 2.2 |  |  | V |
| $\mathrm{I}_{\mathrm{LK}}$ | SHDN, PWM Input Leakage Current | $\mathrm{V}_{\text {PWM }}=\mathrm{V}_{\text {SHLD }}=\mathrm{V}_{\text {DD }}$ |  | 10 |  | $\mu \mathrm{A}$ |
| Dpwmi | Input PWM Duty Cycle |  | 0 |  | 99 | \% |
| FAULT Output |  |  |  |  |  |  |
| $\mathrm{V}_{\text {Eaultiow }}$ | FAULT Logic Output Low | $\mathrm{I}_{\text {sink }}=1 \mathrm{~mA}$ |  |  | 0.4 | V |
| $\mathrm{I}_{\text {fault }}$ | FAULT Leakage Current | $\mathrm{V}_{\text {FaUlit }}=3.3 \mathrm{~V}$, No Faults |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| Thermal Protection |  |  |  |  |  |  |
| $\mathrm{T}_{\text {I(SD) }}$ | T, Thermal Shutdown Threshold |  |  | 150 |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {(SDO-HY) }}$ | $\mathrm{T}_{\text {J }}$ Thermal Shutdown Hysteresis | Maintains previous dimming setting |  | 15 |  | ${ }^{\circ} \mathrm{C}$ |

[^2]
## Typical Characteristics




Boost Efficiency vs PWM Duty Cycle ( $\mathrm{L}=4.7 \mu \mathrm{H} ; \mathrm{V}_{\mathrm{DD}}=\mathrm{PWM}=5 \mathrm{~V}$; $\mathrm{I}_{\mathrm{OUT}}=30 \mathrm{~mA} / \mathrm{ch}$ )



UVLO vs Temperature


Current Limit vs Temperature


## Typical Characteristics



## Shutdown Current vs Input Voltage



Current Sink Accuracy vs Temperature
$\left(\mathrm{V}_{\text {IN }}=12 \mathrm{~V} ; \mathbf{3 0 \mathrm { mA } / \mathrm { ch } )}\right.$



Frequency vs Temperature
( $\mathrm{V}_{\text {w }}=12 \mathrm{~V}$ )


Current Sink Matching vs Temperature ( $\mathrm{V}_{\text {IN }}=12 \mathrm{~V} ; 30 \mathrm{~mA} / \mathrm{ch}$ )


## Typical Characteristics



Enable High Threshold Voltage vs. Input Voltage



Time ( $400 \mathrm{~ns} / \mathrm{div}$ )

Low Side Switch On Resistance vs Temperature



Start UP
$\left(V_{\mathrm{IN}}=12 \mathrm{~V} ; \mathrm{V}_{\text {OUT }}=40 \mathrm{~V}\right.$; $\mathrm{I}_{\text {OUT }}=65 \mathrm{mV}$; Duty Cycle $\left.=50 \%\right)$


Time (2ms/div)

## Typical Characteristics



Time ( $200 \mu \mathrm{~s} / \mathrm{div}$ )

PWM Switching Waveforms
$\left(\mathrm{V}_{\text {IN }}=12 \mathrm{~V}\right.$; $\mathrm{V}_{\text {out }}=40 \mathrm{~V}$; Duty Cycle $=50 \%$ )


Time ( $200 \mu \mathrm{~s} / \mathrm{div}$ )

## Functional Block Diagram



## Functional Description

The AAT1451 adopts a synchronous peak current detect step-up structure to drive up to 48 white LEDs with up to 30 mA each ( 120 mA total) for backlight solutions. The controller derives output feedback from the lowest sink voltage of the four LED sink channels while maintaining the programmed current accuracy and matching. This ensures the lowest possible output voltage, highest efficiency, and continuous operation with mismatched LED strings. LED dimming is controlled by an external 100 Hz to 10 kHz PWM signal. The LED current is on/off with fixed frequency of 8 kHz with the same duty cycle as the PWM signal. This feature, together with the phase shifting feature, makes it easy to filter the LED current switching noise on the output when designing the system.

The AAT1451 is designed for maximum flexibility allowing unused current sinks to be disabled by connecting them to ground. The unique high voltage current sinks support non-matching LED strings (LED quantity, type, etc.)

The boost switching frequency is programmable from 600 kHz up to 1 MHz by external resistor for optimum efficiency and the smallest external filter components. Current mode control provides fast response to line and load transients. Integrated light-load mode ensures highest efficiency across the entire input voltage and load range.

The AAT1451 integrates several fault protection features to deal with LED opens/shorts and thermal faults. Fault tolerant circuitry extends system life by disabling current sinks with open LEDs. The high voltage current sinks maintain normal operation with non-matched strings while also preventing damage due to shorted LEDs. When all LED sinks are open, the over voltage protection is active to prevent the boost output voltage from becoming too high by disabling power MOSFET switching when the OVP voltage threshold is exceeded.
Boost switching is re-enabled when OVP hysteresis is satisfied. Over-current protection prevents inductor saturation and any resulting damage to the switching device occurring during an overload fault condition.

## SwitchRegTM

## Boost Converter Switching Frequency

The AAT1451's boost converter frequency can be adjusted between 600 kHz to 1 MHz using an external resistor ( $\mathrm{R}_{\mathrm{FS}}$ ). For maximum accuracy, a $1 \%$ tolerance resistor is recommended.

Please refer to Table 1 and Figure 1 for $R_{F S}$ resistor values.

$$
\mathrm{R}_{\mathrm{FS}}=\frac{2 \cdot 10^{10}}{\mathrm{~F}_{\mathrm{SW} /}}
$$

| $\mathbf{R}_{\mathbf{F s}}$ (k尺) | Frequency (kHz) |
| :---: | :---: |
| 20 | 1000 |
| 22 | 909 |
| 24 | 833 |
| 26 | 769 |
| 28 | 714 |
| 30 | 667 |
| 33 | 606 |

Table 1: Examples of Standard 1\% R Rss Values for Setting Switching Frequency.


Figure 1: Switch Frequency vs. $\mathrm{R}_{\mathrm{Fs}}$

## Maximum LED Current Selection

The current sink is controlled by the internal reference voltage $\left(\mathrm{V}_{\text {ISET }}\right)$ and the external resistor ( $\mathrm{R}_{\text {SET }}$ ) at the ISET pin. The maximum LED current programmable range is from 15 mA to 30 mA by $\mathrm{R}_{\text {SEт. }}$. For maximum accuracy, a $1 \%$ tolerance resistor is recommended.

The $R_{\text {Set }}$ value can be calculated as follows:

$$
\mathrm{R}_{\mathrm{SET}}=\frac{\text { CurrentSetRatio } \cdot \mathrm{V}_{\text {ISET }}}{\mathrm{I}_{\mathrm{FB}}}
$$

Where CurrentSetRatio $=264$ and $\mathrm{V}_{\text {ISET }}=0.6 \mathrm{~V}$.
For example, if the maximum current for each string LEDs is 30 mA , this corresponds to a minimum resistor of $5.23 \mathrm{k} \Omega$.

$$
\mathrm{R}_{\text {SET }}=\frac{264 \cdot 0.6 \mathrm{~V}}{30 \mathrm{~mA}}=5.23 \mathrm{k} \Omega
$$

| Maximum LED Current (mA) | $\boldsymbol{R}_{\text {SET }}(\mathrm{k} \Omega$ ) |
| :---: | :---: |
| 30 | 5.23 |
| 25 | 6.34 |
| 22 | 7.5 |
| 20 | 7.87 |
| 15 | 10.5 |

Table 2: Examples of Standard 1\% $\mathbf{R}_{\text {SET }}$ Values for Setting Maximum LED Current Levels.

Please also refer to Figure 2 for quickly choosing a $\mathrm{R}_{\text {SET }}$ value.


Figure 2: Choosing an $R_{\text {SEt }}$ Value

## PWM Dimming

The AAT1451 uses a simple PWM interface to control the effective LED current (RMS) at the current sinks. The PWM signal should fit the requirements listed in the electrical characteristic table for proper operation. After initial power-up and SHDN is pulled to high together with PWM high, the device is enabled with $100 \%$ brightness as determined by the $\mathrm{R}_{\text {SEt }}$ resistor value. For example, when the PWM pin is constantly pulled high, which means $100 \%$ duty ratio, the current per channel is typically 30 mA with $\mathrm{R}_{\text {SEt }}=5.3 \mathrm{k} \Omega$. By feeding the PWM pin with a proper PWM signal, the RMS current of each sink is proportional to the duty ratio of the PWM signal. Table 3 shows the average LED current of each channel at maximum 22 mA as the PWM duty cycle change.

The AAT1451 integrates a clock hunting circuitry to derive the external PWM signal duty cycle to generate same duty cycle LED current on/off between the maximum current value and 0 mA with fixed 8 kHz frequency. It can work bi-directionally when the PWM signal increases or decreases to determine the duty cycle.

| PWM Duty Cycle | FB1 - FB4 Current (mA) |
| :---: | :---: |
| (Raser $=7.5 \mathrm{KQ}$ ) |  |$|$| $100 \%$ | 22 |
| :---: | :---: |
| $95 \%$ | 19 |
| $90 \%$ | 18 |
| $85 \%$ | 17 |
| $80 \%$ | 16 |
| $75 \%$ | 15 |
| $70 \%$ | 14 |
| $65 \%$ | 13 |
| $60 \%$ | 12 |
| $55 \%$ | 11 |
| $50 \%$ | 9 |
| $45 \%$ | 8 |
| $40 \%$ | 7 |
| $35 \%$ | 6 |
| $30 \%$ | 5 |
| $25 \%$ | 4 |
| $20 \%$ | 3 |
| $15 \%$ | 2 |
| $10 \%$ | 1 |
| $5 \%$ |  |

Table 3: AAT1451 PWM Duty Cycle vs. LED Current at Maximum 22mA Setting


Figure 3: PWM Duty Cycle vs. LED Current at Maximum 30mA Setting.

## Automatic Phase Shift PWM

The AAT1451 has implemented an automatic phase shift PWM mechanism for FB1-FB4 current sources. It will automatically detect the number of operating channels and phase shift each channel, " n ", by $\Theta_{\mathrm{n}}$ relative to the PWM input.

The phase shift $\Theta$ and delay time $T_{D}$ are defined as:

$$
\begin{gathered}
\Theta_{n}=\frac{360 \cdot(n-1)}{N} \\
T_{D}=\frac{T_{P W M}}{N}
\end{gathered}
$$

Where N is the number of operating channels, and n is the target channel.

The FB1-FB4 timing diagram is shown in Figure 4 to elaborate the automatic phase shift working waveform.


Figure 4: AAT1451 Automatic Phase Shift PWM Timing Diagram

## Open LED Protection and FAULT Indication for Shorted LEDs

The AAT1451 device is protected from faults arising from LED opens and shorts.

An open LED(s) condition will be detected by the controller at startup. The low voltage is detected by the controller which disables the given current sink. The remaining LED strings continue to operate normally. The controller re-enables the disabled current sink in the event that the LED open condition is removed during a power cycle or $\overline{\text { SHDN }}$ cycle. This feature extends backlight life and reliability.

Under the condition that PWM duty cycle is less than $100 \%$, shorted LEDs condition results in a higher voltage appearing on the affected channels' current-sink pin. The affected current sink automatically compensates for the additional voltage. This current sink can withstand a high voltage indefinitely. However, the increased voltage across the current sink causes an increase in power dissipation. The AAT1451 automatically monitors the current sink voltage for two or more shorted LEDs. To prevent thermal shutdown, the shorted LED string is disabled while the remaining strings continue to operate. The shorted LED string remains disabled until a power cycle or SHDN cycle. The open drain FAULT output is
driven low to indicate thermal shutdown and shorted LED condition(s). The FAULT output is latched low during shorted LED fault, and is reset after a power cycle, SHDN cycle or thermal shutdown. To prevent damage, the backlight can be shutdown based on the FAULT output.

## OVP Protection

Under all conditions, the over-voltage protection circuitry prevents the switching node (SW) from exceeding the maximum operating voltage prior to disabling the current sink. Over-voltage protection (OVP) disables boost switching while maintaining the programmed LED current. Boost switching is re-enabled when OVP hysteresis is satisfied.

## Thermal Protection for Over-Current and Short-Circuit

The AAT1451 has a built-in thermal protection circuit that goes into shutdown when the die temperature rises above the thermal limit, as is the case during a LED short-circuit condition. Integrated over-current limit protection is provided. Over-current prevents inductor saturation and any resulting damage to the switching device occurring during an overload fault condition.

## Application Information

## LED Selection

The AAT1451 is specifically intended for driving white LEDs. However, the device design will allow the AAT1451 to drive most types of LEDs with forward voltage specifications typically ranging from 2.2 V to 4.7 V depending upon supply voltage. LED applications may include mixed arrangements for display backlighting, keypad display, and any other application that needs a constant current sink generated from a varying input voltage. Since the FB1 to FB4 constant current sinks are matched within $2 \%$ with negligible supply voltage dependence, the constant current channels will be matched regardless of the specific LED forward voltage ( $\mathrm{V}_{\mathrm{F}}$ ) levels. The low dropout current sinks in the AAT1451 maximize performance and make it capable of driving LEDs with high forward voltages.

## Shutdown

To activate the shutdown operation, the SHDN input for the AAT1451 should be strobed low. In this case, the AAT1451 typically draws less than $40 \mu \mathrm{~A}$ from the input.

## Inductor Selection

The white LED boost (step-up) converter is designed to operate with a $4.7 \mu \mathrm{H}$ inductor for all input and output voltage combinations. The inductor saturation current rating should be greater than the NMOS current limit.

$$
D_{\text {MAX }}=\frac{V_{\text {OUT }}+V_{D}-V_{\text {IN(MIN })}}{V_{\text {OUT }}+V_{D}}
$$

Where:
$\mathrm{V}_{\text {OUT }}$ is the boost converter output voltage;
$V_{D}$ is the forward voltage of Schottky diode;
$\mathrm{V}_{\text {IN(MIN) }}$ is the minimum input voltage.
The output inductor $(\mathrm{L})$ is selected to avoid saturation at minimum input voltage, maximum output load conditions. Peak current may be calculated from the following equation, again assuming continuous conduction mode. Worst-case peak current occurs at minimum input voltage (maximum duty cycle) and maximum load. Switching frequency is estimated at 600 kHz with a $4.7 \mu \mathrm{H}$ inductor.

$$
I_{\text {PEAK }}=\frac{I_{\text {OUT }}}{1-D_{M A X}}+\frac{D_{M A X} \cdot V_{I N(M I N)}}{2 \cdot F_{S} \cdot L}
$$

## Compensation Component Selection

The AAT1451 Main Boost architecture uses peak current mode control to eliminate the double pole effect of the output L\&C filter and simplifies the compensation loop design. The current mode control architecture simplifies the transfer function of the control loop to be a one-pole, one left plane zero and one right half plane (RHP) system in frequency domain. The dominant pole can be calculated by:

$$
f_{P}=\frac{1}{2 \pi \cdot R_{O} \cdot C_{O U T}}
$$

The ESR zero of the output capacitor can be calculated by:

$$
\mathrm{f}_{\mathrm{Z}_{-E S R}}=\frac{1}{2 \pi \cdot \mathrm{R}_{\mathrm{ESR}} \cdot \mathrm{C}_{\mathrm{OUT}}}
$$

Where:
$C_{\text {out }}$ is the output filter capacitor;
$R_{0}$ is the equivalent load resistor value;
$R_{\text {ESR }}$ is the equivalent series resistance of the output capacitor.

The right half plane (RHP) zero can be determined by:

$$
\mathrm{f}_{\mathrm{Z}_{-} \mathrm{ESR}}=\frac{\mathrm{V}_{\mathrm{IN}}{ }^{2}}{2 \pi \cdot \mathrm{~L}_{1} \cdot \mathrm{I}_{\mathrm{OUT}} \cdot \mathrm{~V}_{\mathrm{OUT}}}
$$

It is recommended to design the bandwidth to one decade lower than the frequency of RHP zero to guarantee the loop stability. A series capacitor and resistor network ( $\mathrm{R}_{\text {comp }}$ and $\mathrm{C}_{\text {сомр }}$ ) connected to the COMP pin sets the pole and zero which are given by:

$$
\begin{aligned}
\mathrm{f}_{\mathrm{P}_{-} \text {COM }} & =\frac{1}{2 \pi \cdot \mathrm{R}_{\mathrm{EA}} \cdot \mathrm{C}_{\mathrm{COMP}}} \\
\mathrm{f}_{\mathrm{Z}_{-} \text {СOM }} & =\frac{1}{2 \pi \cdot \mathrm{R}_{\mathrm{COMP}} \cdot \mathrm{C}_{\mathrm{COMP}}}
\end{aligned}
$$

Where:
$\mathrm{C}_{\text {сомр }}$ is the compensation capacitor;
$\mathrm{R}_{\text {comp }}$ is the compensation resistor;
$R_{E A}$ is the output resistance of the error amplifier (M $\Omega$ ).
A 15 nF capacitor and a $20 \mathrm{k} \Omega$ resistor in series are chosen for optimum phase margin and fast transient response.

## Capacitor Selection

Careful selection of the external capacitor $\mathrm{C}_{\text {IN }}$ is important because it will affect turn-on time and transient performance. Optimum performance will be obtained when low equivalent series resistance (ESR) ceramic capacitor is used; in general, low ESR may be defined as less than $100 \mathrm{~m} \Omega$. A value of $2.2 \mu \mathrm{~F}$ for the input capacitor is a good starting point when choosing a capacitor. If the constant current sinks are only programmed for light current levels then the input capacitor size may be decreased.

## Capacitor Characteristics

Ceramic composition capacitor is highly recommended over all other types of capacitors for use with the AAT1451. Ceramic capacitors offer many advantages over their tantalum and aluminum electrolytic counterparts. A ceramic capacitor typically has very low ESR, is lower cost, has a smaller PCB footprint, and is nonpolarized. Since ceramic capacitors are non-polarized, they are not prone to incorrect connection damage.

## Equivalent Series Resistance

ESR is an important characteristic to consider when selecting a capacitor. ESR is a resistance internal to a capacitor that is caused by the leads, internal connections, size or area, material composition, and ambient temperature. Capacitor ESR is typically measured in milliohms for ceramic capacitors and can range to more than several ohms for tantalum or aluminum electrolytic capacitors.

## Ceramic Capacitor Materials

Ceramic capacitor less than $0.1 \mu \mathrm{~F}$ are typically made from NPO or COG materials. NPO and COG materials generally have tight tolerance and are very stable over temperature. Larger capacitor values are usually composed of X7R, X5R, Z5U or Y5V dielectric materials. Large ceramic capacitors (i.e. larger than $4.7 \mu \mathrm{~F}$ ) are often available in low cost Y5V and $\mathrm{Z5U}$ dielectrics, but capacitors larger than $4.7 \mu \mathrm{~F}$ are not typically required for

## AAT1451 applications.

Capacitor area is another contributor to ESR. Capacitors that are physically large will have a lower ESR when compared to an equivalent material smaller capacitor. These larger devices can improve circuit transient response when compared to an equal value capacitor in a smaller package size.

## PCB Layout Considerations

When designing a PCB for the AAT1451, the key requirements are:

1. Place the input and output decoupling capacitors $\mathrm{C}_{\mathrm{IN}}$ and Cout as close to the chip as possible to reduce switching noise and output ripple.
2. Place the bypass capacitor $\mathrm{C}_{\text {vod }}$ as close to the chip as possible.
3. Keep the power traces (GND, SW, and VIN) short, direct, and wide to allow large current flow. Place sufficient multiple-layer pads when needed to change the trace layer.
4. Connect the output capacitor $\mathrm{C}_{\text {out, }}$ output inductor L1 and Schottky diode DS1 as close as possible. Use connections as short as possible for L1 to the SW pins and place no signal lines under the inductor.
5. Place the peripheral components like $\mathrm{R}_{\text {comp, }} \mathrm{C}_{\text {comp, }} \mathrm{R}_{\text {SET }}$ and $\mathrm{R}_{\mathrm{FS}}$ as close to the chip as possible.

## Evaluation Board User Interface

The user interface for the AAT1451 evaluation board is provided by three buttons and two connection terminals. The board is operated by supplying external power and pressing individual buttons. Table 4 indicates the function of each button or button combination. To power-on the evaluation board, connect a power supply or battery to both the VIN (with 5 to 26 V ) and the VCC (with 2.2 to 5 V ) terminals.

A red LED indicates that VCC power is applied which is necessary to enable the AAT1451. Once one button is pressed, the green LED will flash once to indicate that the related action is processed.

## User Interface Functionality

| Button(s) Pushed | Description |
| :---: | :--- |
| UP | [Push/Release once] Channels FB1 to FB4 are turned on with 1mA per channel. With every push/release <br> the current is increased according to Table 3. |
| DOWN | $[$ [Push/Release once] Channels FB1 to FB4 are turned on with 22mA per channel. With every push/re- <br> lease the current is decreased according to Table 3. |
| CYCLE | $[$ [Push/Release once] Auto cycling up and down. |

Table 4: AAT1451 Evaluation Board User Interface.


Figure 5: AAT1451 Evaluation Board Schematic.

a: Top Side

## b: Bottom Side

Figure 6: AAT1451 Evaluation Board Layout.

| Component | Part Number | Description | Manufacturer |
| :---: | :---: | :---: | :---: |
| U1 | AAT1451 | High Efficiency White Backlight LED Driver | Analogic Tech |
| U2 | PIC12F675 | 8-bit CMOS, FLASH-based $\mu \mathrm{C}$; 8-pin PDIP package | Microchip |
| S1-S3 | PTS645TL50 | Switch Tact, SPST, 5mm | ITT Industries |
| $\mathrm{R}_{\text {comp, }} \mathrm{R}_{\text {FS }}$ | Chip Resistor | 20k $\Omega, 1 \%, 1 / 4 \mathrm{~W} ; 0603$ | Vishay |
| $\mathrm{R}_{\text {SET }}$ | Chip Resistor | 7.5k $\Omega, 1 \%, 1 / 4 \mathrm{~W} ; 0603$ | Vishay |
| R1 | Chip Resistor | $42.7 \mathrm{k} \Omega, 1 \%, 1 / 4 \mathrm{~W} ; 0603$ | Vishay |
| R2 | Chip Resistor | $1.2 \mathrm{k} \Omega, 1 \%, 1 / 4 \mathrm{~W} ; 0603$ | Vishay |
| R3, R4, R5 | Chip Resistor | 10k $\Omega, 1 \%, 1 / 4 \mathrm{~W}$; 0603 | Vishay |
| R6 | Chip Resistor | 330ת, 1\%, 1/4W; 0603 | Vishay |
| R7, R8, R9, R10 | Chip Resistor | 1k , 1\%, 1/4W; 0603 | Vishay |
| $\mathrm{C}_{\text {IN }}, \mathrm{C}_{\text {OUT }}$ | GRM31CR71H225KA88 | $2.2 \mu \mathrm{~F}, ~ 50 \mathrm{~V}, \mathrm{X} 7 \mathrm{R}, 1206$ | Murata |
| $\mathrm{C}_{\text {VDD }}$ | GCM188R70J225KE22 | $2.2 \mu \mathrm{~F}, 6.3 \mathrm{~V}, \mathrm{X} 7 \mathrm{R}, 0603$ | Murata |
| $\mathrm{C}_{\text {comp }}$ | GRM188R71H153KA01 | 15nF, 50V, X7R, 0603 | Murata |
| C1, C2 | GRM188R71H104KA93 | $0.1 \mu \mathrm{~F}, ~ 50 \mathrm{~V}, \mathrm{X7R}$, 0603 | Murata |
| L1 | SD53-4R7-R | $4.7 \mu \mathrm{H}, 45 \mathrm{~m} \Omega, 2.01 \mathrm{~A}, 20 \%$ | Coiltronics |
| DS1 | SS16L | $1.0 \mathrm{~A}, 60 \mathrm{~V}$ Surface Mount Schottky Barrier Rectifier | TSC |
| LED1 | CMD15-21SRC/TR8 | Red LED; 1206 | Chicago Miniature Lamp |
| LED2 | CMD15-21UGC/TR8 | Green LED; 1206 | Chicago Miniature Lamp |

Table 5: AAT1451 Evaluation Board BOM List.

| Manufacturer | Part Number | L ( $\boldsymbol{\mu H}$ ) | Max DCR (ms) | Saturation Current (A) | Size WxLxH (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Murata | LQH6PPN4R7M43 | 4.7 | 20 | 3.2 | $6.0 \times 6.0 \times 4.3$ |
|  | LQH6PPN6R8M43 | 6.8 | 28 | 2.8 |  |
| Coiltronics | SD53-4R7-R | 4.7 | 45 | 1.65 |  |
|  | SD53-6R8-R | 6.8 | 68 | 2.01 |  |

Table 6: Surface Mount Inductors.

| Manufacturer | Part Number | Value ( $\mu \mathrm{F}$ ) | Voltage (V) | Tolerance | Temp. Co. | Case |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Murata | GCM188R70J225KE22 | 2.2 | 6.3 | 10\% | X7R | 0603 |
|  | GRM188R71H153KA01 | 0.015 | 50 | 10\% | X7R | 0603 |
|  | GRM188R71H104KA93 | 0.1 | 50 | 10\% | X7R | 0603 |
|  | GRM31CR71H225KA88 | 2.2 | 50 | 10\% | X7R | 1206 |
| AVX | 06036C225KAT | 2.2 | 6.3 | 10\% | X7R | 0603 |
|  | 06035C163KAT | 0.015 | 50 | 10\% | X7R | 0603 |
|  | 06035C104KAT | 0.1 | 50 | 10\% | X7R | 0603 |
|  | 12065C225KAT | 2.2 | 50 | 10\% | X7R | 1206 |
| KEMET | C0603C225K9RAC | 2.2 | 6.3 | 10\% | X7R | 0603 |
|  | C0603C153K5RAC | 0.015 | 50 | 10\% | X7R | 0603 |
|  | C0603C104K5RAC | 0.1 | 50 | 10\% | X7R | 0603 |
|  | C1206C225K5RAC | 2.2 | 50 | 10\% | X7R | 1206 |

Table 7: Surface Mount Capacitors.

## Single Li-ion Cell Powered Application:

Figure 7 demonstrates a backlight solution for single cell Li-ion battery powered application using the AAT1451 to drive the WLEDs and the AAT3110 regulated charge pump to supply the internal regulator of AAT1451. The AAT1451
plus AAT3110 solution is adopted to drive 6 series-4 parallel (6S4P) to 8 series-4 parallel (8S4P) typical of 13 " and smaller sized displays. Figure 8 shows the efficiency.


Figure 7: Schematic of AAT1451 plus AAT3110


Figure 8: Efficiency vs ILED for driving 8series - 4parallel (8S4P) LEDs

| Package | Part Marking $^{1}$ | Part Number (Tape and Reel) ${ }^{2}$ |
| :---: | :---: | :---: |
| TDFN34-16 | N5XYY | AAT1451IRN-T1 |

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## Package Information

TDFN34-16


Top View


Bottom View


Detail "A"


All dimensions in millimeters.

1. $X Y Y=$ assembly and date code.
2. Sample stock is generally held on part numbers listed in BOLD.

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[^0]:     exceeded.

[^1]:     specified is not implied.
    2. Based on long-term current density limitation.
    3. Mounted on an FR4 board.
    4. Derate $20 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $25^{\circ} \mathrm{C}$.

[^2]:    
    tion with statistical process controls.
    2. Output voltage must result in a voltage lower than the SW maximum ratings under all operating conditions

